

Wolfgang Windsteiger Research Institute for Symbolic Computation (RISC) Johannes Kepler University Linz (JKU)

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- User Interface: prepare mathematical document + support activities whose results get incorporated into the document.



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ALL IN ONE DOCUMENT



Theorema Theory = Theorema notebook + Theorema archive

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- in a format that can be imported into Theorema again



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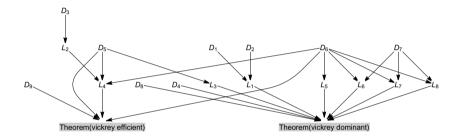
Theorema notebook: mathematical document (see above).

Theorema archive:

- file containing formulas only
- in a format that can be imported into Theorema again
- in other formats to be read by other systems, eg. MMT (Kohlhase/Rabe)



Work in progress: Automatically maintain and display a formula graph such as



where

vertices are formula labels and

 $\blacksquare X \to Y \text{ means: formula } X \text{ is needed in the proof of formula } Y.$

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Features supported in the interactive graphical user interface (Theorema commander):

Tooltip over label shows entire formula (see labels in proofs).



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- Apply graph algorithms in order to investigate theory structure.



Prerequisite for dynamically maintaining the formula graph: tracking of formula dependencies.



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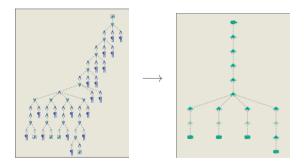
Naive approach: Add edges $(k_1, G), \ldots, (k_n, G)$ to the formula graph.

But: It is not guaranteed, that all of the k_1, \ldots, k_n are really required for proving *G*. Solution:

PROOF SIMPLIFICATION.

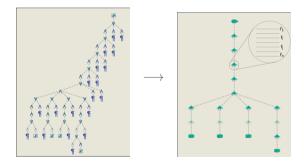


1. Eliminate unnecessary paths in the proof tree



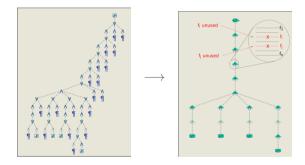


- 1. Eliminate unnecessary paths in the proof tree
- 2. Eliminate unnecessary formulas in each node



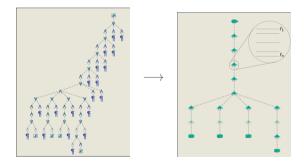


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DETECTION OF UNNECESSARY FORMULAS

Proof tree node: proof situation (proof goal + knowledge base + additional prover info)



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Proof info: contains information necessary for displaying proof in human-readable form, eg. formulas needed to perform the proof step.



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Proof tree node (detail): proof info + proof situation

Proof info: contains information necessary for displaying proof in human-readable form, eg. formulas needed to perform the proof step.

Proof info cannot be extracted automatically, it has to be specified when implementing the prover.



Proof Step: Reduce proof goal g by knowledge k_i to new goal g'.

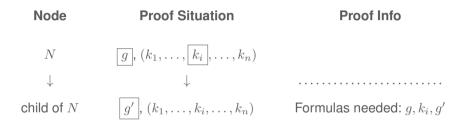


Proof Step: Reduce proof goal g by knowledge k_i to new goal g'.

Node	Proof Situation	Proof Info
N	$g, (k_1, \ldots, k_i, \ldots, k_n)$	
\downarrow	\downarrow	
child of N	$g', (k_1, \ldots, k_i, \ldots, k_n)$	



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N	$g, (k_1, \ldots, k_i, \ldots, k_n)$	
\downarrow	\downarrow	
child of N	$g', (k_1, \ldots, k_i, \ldots, k_n)$	Formulas needed: g, k_i, g'

Proof info allows to generate text:

"In order to prove g, because of k_i , it is sufficient to prove g'."



PROOF INFO: FORMULAS NEEDED

Instead of plain list (f_1, \ldots, f_n)



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Instead of plain list (f_1, \ldots, f_n)

$$\longrightarrow$$
 $((u_1,\ldots,u_m),(g_1,\ldots,g_m))$

where

 u_i are sets of formulas used and

 g_i are sets of formulas generated in a node, st.

all formulas in u_i are needed to generate the formulas in g_i .



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Example above: $((\{g, k_i\}), (\{g'\}))$.



Node

Proof Info

Necessary Formulas

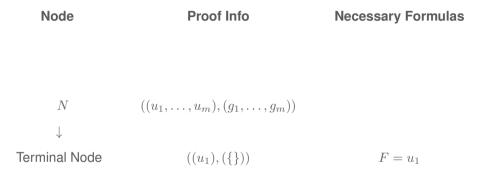
Terminal Node

 $((u_1), (\{\}))$

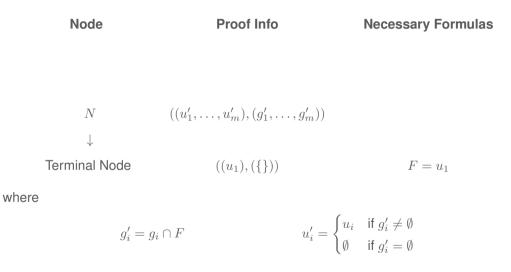
 $F = u_1$



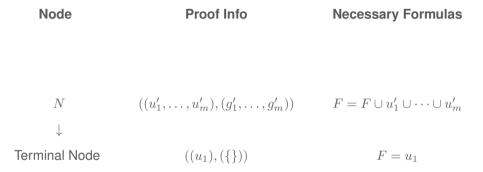




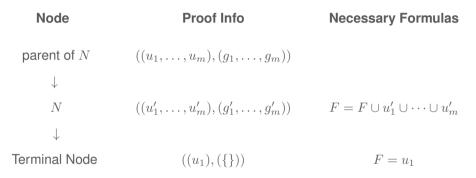




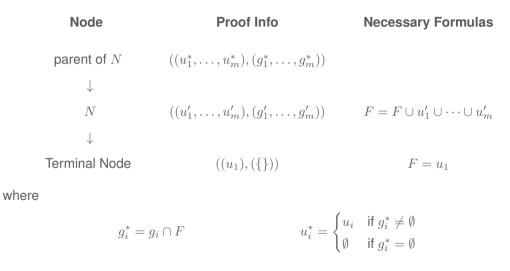














Node	Proof Info	Necessary Formulas
parent of N	$((u_1^*,\ldots,u_m^*),(g_1^*,\ldots,g_m^*))$	$F = F \cup u_1^* \cup \dots \cup u_m^*$
\downarrow		
N	$((u_1',\ldots,u_m'),(g_1',\ldots,g_m'))$	$F = F \cup u'_1 \cup \dots \cup u'_m$
\downarrow		
Terminal Node	$((u_1), (\{\}))$	$F = u_1$

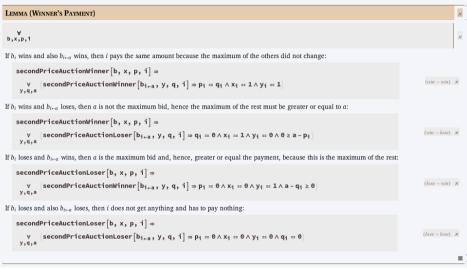


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N	$((u_1',\ldots,u_m'),(g_1',\ldots,g_m'))$	$F = F \cup u'_1 \cup \dots \cup u'_m$
\downarrow		
Terminal Node	$((u_1), (\{\}))$	$F = u_1$

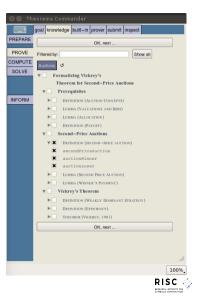
Upon termination: *F* contains all necessary formulas!

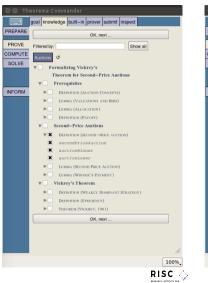
Root node proof info: $((\{\}), (K^*))$ where K^* contains just those formulas of the original knowledge base that were actually needed.

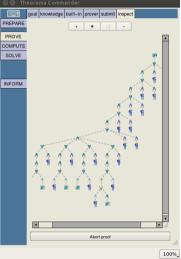












▼ Ø Proof of (lose			-win) #4 :	<u>Show</u> pro	<u>oof</u>
		knowledge	built-in	prover	Restore settings
		secondPriceA	uction, au	ctionWinne	r, auctionLoser

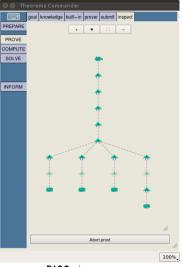


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Proof Simplification	
We prove:	1 🖻
$ \begin{array}{l} \forall \text{secondPriceAuctionLoser}(b, \ x, \ p, \ i) \Rightarrow \\ b_i x_i p_i \end{array} $	
$\left(\bigvee_{y,q,\sigma} \texttt{secondPriceAuctionWinner} \{ b_{i=a}, y, q, i \} \Rightarrow ((p_i = 0) \land (x_i = 0) \land (y_i = 1) \land ((a - q_i) \ge 0)) \right)$	(lese-win)
under the assumptions:	
\mathbf{v} secondPriceAuction $[b,\ x,\ p,\ n]$:=> bid[b, n] ^ allocation $[x,\ n]$ ^ payment[p, n] ^ b	1
	(secondPriceAuction)
$\left[\underbrace{\underset{j \in 1_{i-1}, i}{3}}_{j \in i} \text{ secondPriceAuctionWinner}[b, x, p, i] \land \left[\underbrace{\underset{j \in 1_{i-1}, i}{3}}_{j \in i} \text{ secondPriceAuctionLoser}[b, x, p, j] \right] \right],$	
$ \begin{array}{l} \forall secondPriceAuctionWinner\left[b \ , \ x \ , \ p \ , i \right] \ iee \ \left(b_i = \max\left\{b\right\}\right) \land \left(x_i = 1\right) \land \left(p_i = \max\left\{b_{ie}\right\}\right) \ , \\ b_j x_i \ p_j i \end{array}$	(anetionWinner)
$\forall \texttt{secondPriceAuctionLoser}[b, x, p, i] : \Longleftrightarrow (x_i = 0) \land (b_i \le \max\{b_{i+1}\}) \bullet (b_i \le \max\{b_$	(auctionLoser)
We have several alternatives to continue the proof.	
For proving (lose=win) we choose b, x, p, and i arbitrary but fixed and show	
secondPriceAuctionLoser[b , x , p , i] \Rightarrow	
$\left(\bigvee_{y \in q, a} \texttt{secondPriceAuctionWinner} \left[b_{i+a}, y, q, i \right] \Rightarrow \left(\left(p_i = 0 \right) \land \left(x_i = 0 \right) \land \left(y_i = 1 \right) \land \left(\left(a - q_i \right) \ge 0 \right) \right) \right).$	(G#0)
We have several alternatives to continue the proof.	
a Alternative 1:	
In order to prove (G#0) we assume	
<pre>secondPriceAuctionLoser[b, x, p, /]</pre>	(A#2)
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File Edit Insert Format Cell Graphics Evaluation Palettes Window Help Proof Simplification Eliminate failing/pending branches K Eliminate superfluous steps × Eliminate unused formulae We prove: x secondPriceAuctionLoser(h, x, n, i) = v secondPriceAuctionWinner[$b_{i=a}$, y, q, i] \Rightarrow ($(p_i = 0) \land (x_i = 0) \land (y_i = 1) \land ((a - q_i) \ge 0))$ under the assumptions: y secondPriceAuction(b, x, p, n) t⇔ bid(b, n) ∧ allocation(x, n) ∧ payment(p, n) ∧ ∃ secondPriceAuctionWinner[b, x, p, i] ∧ v secondPriceAuctionLoser(b, x, p, i) . y secondPriceAuctionWinner[b, x, p, i] :⇔ $(b_i = \max\{b\}) \land (x_i = 1) \land (p_i = \max\{b\}_i, 1)$, ∀ secondPriceAuctionLoser(b_i , x_i , p_i , i] :⇔ ($x_i = 0$) ∧ ($p_i = 0$) ∧ ($b_i \le \max\{b_{i_n}\}$). We have several alternatives to continue the proof. Alternative 1: For proving (lose=win) we choose b, x, p, and i arbitrary but fixed and show secondPriceAuctionLoser [b, x, p, I] \Rightarrow ∀ secondPriceAuctionWinner[b_{ieq} , y, q, i] ⇒ (($p_i = 0$) ∧ ($x_i = 0$) ∧ ($y_i = 1$) ∧ (($a - q_i$) ≥ 0)). We have several alternatives to continue the proof 1 a la RISC @ 100%

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		(($p_i = 0) \land$	$\{x_i =$	$0) \land (y_i = 1$	$) \land ((a - q_i))$	≥ 0))						
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	b	$, \pi, p, i$				[b, x, p, i	1.000				(81	(tionWinner)	
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	ь	v se	condPrie	eAuc	tionLoser	b, x, p, i]	1 em (x _i =)	a) ∧ (p _i =	0) ∧ (b _i ≤	max [b _{i+-}]). (suctionLoser)	
	For pr	roving (Le	<u>se=win</u>) W	e cho	ose b, x, p,	and i arbitra	ry but fixed	and show	,				
	s	econdPr	iceAuct	ionLo	ser[b, x,	$\rho, i] \Rightarrow \begin{pmatrix} \forall \\ y, q \end{pmatrix}$	secondPr	iceAucti	onWinner	[<i>b</i> _{iea} , y,	<i>q</i> , <i>i</i>] ⇒		
						$) \land ((a - q_i))$						(G#0)	
	In ord	er to pro	ve (<u>G#0</u>) v	ve ass	sume								
	s	econdPr	iceAuct	ionLo	ser[b, x,	p, /]						(A#2)	
	and th	nen prov	Ð										
	y	v sec	ondPrice	Aucti	onWinner[b _{i+a} , y, q,] ⇒					(Ge3)	
		((p) =	= 0) ^ (X)	= 0)	$(y_{1} = 1)$	$((a - q_i) \ge$	8)).					(010)	
	For pr	roving (G	#3) we ch	loose	y, q, and a	arbitrary but	fixed and s	how					
	s	econdPr	iceAuct	ionWi	nner [b _{i+a} ,	$y, q, i] \Rightarrow ($	$(p_i = 0) \land$	$(x_i = 0) \land$	$(y_i = 1) \land$	$((a - q_i))$	≥ 0)).	(G#7)]	
	In ord	er to pro	ve (<u>G#7</u>) v	ve ass	sume								
	s	econdPr	iceAuct	ionWi	nner[b _{i⊷a} ,	y,q,/]						(A#11)]	
		nen prov											
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- Formula dependency graph is a nice/valuable tool for theory exploration/development.





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- Formula dependency graph is a nice/valuable tool for theory exploration/development.
- Proof simplification is a necessary requirement, if we want to automatically maintain a formula dependency graph.

