# Lecture 3 Order Bases The Sigma Basis Algorithm

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1. Power Hermite-Padé Approximants

2. Order and Defect

3. Sigma Basis Algorithm

4. Complexity

#### Preamble

In lecture 3 we take a different approach to compuing our equations of the form

$$a_1(z)p_1(z) + \cdots + a_m(z)p_m(z) = O(z^{\sigma})$$

In this case we separate satisfying the order condition with also trying the satisfy the degree bounds. We also show how these same methods can be used to solve the case where the  $a_i(z)$ are vectors of power series. We then present the sigma-basis algorithm, a contructive procedure for determining an order basis (also sometimes a sigma basis or a minimal approximant basis). We give both a simple algorithm quadratic in the order and a recursive algorithm which computes with quasi-linear complexity.

This work was done jointly with Bernhard Beckermann.

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  - e.g. describes recursive computation
- Still not so precise for Hermite-Padé, matrix problems, etc

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Describe <u>all</u> well-known approx problems uniformly.

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- Include both scalar and matrix versions
- Describe *all* solutions to such problems.
- Provide algorithm to efficiently compute such solutions.
  - Uniformize to model Hermite-Padé approximants
  - Model algorithm on Hermite-Padé computation

#### **Problem and Techniques**

Recall our problem:

Given G(z) ∈ K<sup>s×m</sup>[[z]], some degree constraints and order σ find solutions to G(z) · P(z) = O(z<sup>σ</sup>) satisfying degree constraints.

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Insight I:

> Treat order part and degree parts separately.

Insight II:

- Make things look like Hermite-Padé problem
- Solve Hermite-Padé problem.
- Show similar techniques work in more general case.

# Power Hermite-Padé Approximants

#### Vector Hermite Padé Approximants

Deal with vector problem by converting to scalar problem.

$$\mathbf{G}(z)\cdot\mathbf{P}(z)=z^{\vec{v}}\mathbf{R}(z)$$

converted to scalar problem via

$$\mathbf{A}(z) = [1, z, \dots, z^{s-1}]\mathbf{G}(z^s)$$

Order problem now given by

$$\mathbf{A}(z)\cdot\mathbf{P}(z^s)=z^{\sigma}\mathbf{S}(z).$$

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Same as

$$\begin{aligned} f_0(z)p_1(z) + g_0(z)p_2(z) &= z^{\tau}r_0(z) \\ f_1(z)p_1(z) + g_1(z)p_2(z) &= z^{\tau}r_1(z) \end{aligned}$$

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Thus  $\mathbf{A}(z)\mathbf{P}(z^2) = z^{\sigma}\mathbf{S}(z)$  same as  $\mathbf{G}(z)\mathbf{P}(z) = z^{\tau}\mathbf{R}(z)$ 

#### Another Example

$$\mathbf{G}(z) = \begin{bmatrix} f_0(z) & g_0(z) & h_0(z) \\ f_1(z) & g_1(z) & h_1(z) \\ f_2(z) & g_2(z) & h_2(z) \end{bmatrix}$$

 $\mathbf{G}(z)\mathbf{P}(z) = z^{\mathsf{T}}\mathbf{R}(z)$  gives

$$\mathbf{A}(z) = [f_0(z^3) + zf_1(z^3) + z^2f_2(z^3), \\ g_0(z^3) + zg_1(z^3) + z^2g_2(z^3), \\ h_0(z^3) + zh_1(z^3) + z^2h_2(z^3)]$$

 $\mathbf{A}(z)\mathbf{P}(z^3) = z^{\sigma}\mathbf{S}(z)$  with  $\mathbf{P} = [p_1, p_2, p_3]^T$  then gives

$$\begin{aligned} f_0(z)p_1(z) + g_0(z)p_2(z) + h_0(z)p_3(z) &= z^{\tau}r_0(z) \\ f_1(z)p_1(z) + g_1(z)p_2(z) + h_1(z)p_3(z) &= z^{\tau}r_1(z) \\ f_2(z)p_1(z) + g_2(z)p_2(z) + h_2(z)p_3(z) &= z^{\tau}r_2(z) \end{aligned}$$

#### Power Hermite-Padé

Let  $\sigma \ge 0$ , s > 0,  $n_1, \ldots, n_m$  be integers,  $n_l \ge -1$ 

Definition (Power Hermite Padé approximant)  $\mathbf{P} = (p_1, \dots, p_m)$  of PHPA of type  $(\mathbf{n}, \sigma, s)$  consists of scalar polynomials  $p_l$  having degrees bounded by the  $n_l$  with

$$\mathbf{A}(z) \cdot \mathbf{P}(z^s) = a_1(z)p_1(z^s) + \ldots + a_m(z)p_m(z^s) = c_{\sigma} z^{\sigma} + \cdots$$

Generalizes

- Hermite-Padé, Simultaneous-Padé, etc
- vector and matrix versions of the above

Given :  $\mathbf{A} = (a_1, \ldots, a_m) \in \mathbb{K}^m[[z]]$  with  $a_m(0) \neq 0$ .

Definition (Order) The *order* of a  $\mathbf{P} = (P_1, \dots, P_m) \in \mathbb{K}^m[z]$ 

ord  $\mathbf{P} := \sup\{\sigma \in \mathbb{N}_0 : \mathbf{A}(z) \cdot \mathbf{P}(z^s) = z^{\sigma} \cdot R(z) \text{ with } R \in \mathbb{K}[[z]]\}.$ 

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**Definition** (Defect)

The *defect* of  $\mathbf{P} = (P_1, \ldots, P_m) \in \mathbb{K}^m[z]$  (w.r.t.  $\mathbf{n} = (n_1, \ldots, n_m)$ ):

$$dct \mathbf{P} := \min_{l} \{n_l + 1 - deg P_l\}$$

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defect is a measure of closeness to set of degree bounds

#### Defect, Order (cont.)

• 
$$dct \mathbf{P} > 0$$
 same as  $deg P_{\ell} \le n_{\ell}$  for all  $\ell$ .

Hermite-Padé problem is same as : find P in

$$\mathcal{L}^{\sigma} = \{ \mathbf{P} \in \mathbb{K}^{m}[z] : dct \, \mathbf{P} > 0, ord \, \mathbf{P} \ge \sigma \}$$

where 
$$\sigma = n_1 + \cdots + n_m + m - 1$$
.

In general look at

$$\mathcal{L}^{\sigma} = \{ \mathbf{P} \in \mathbb{K}^m[z] : dct \, \mathbf{P} > 0, ord \, \mathbf{P} \ge \sigma \}$$

for arbitary  $\sigma$ .

## Sigma Basis Algorithm

#### **Recall : Order Bases**

Let  $\sigma \in \mathbb{N}_0$ .

#### **Definition (Order Bases)**

The system  $\mathbf{P}_1, \ldots, \mathbf{P}_m \in \mathbb{K}^m[z]$  is called an *order-basis* if:

(a) ord  $P_{\ell} \ge \sigma$  for all  $\ell$ ,

**(b)** For each  $\mathbf{F} \in \mathcal{L}^{\sigma}$  there exists one and only one tuple of polynomials  $(\alpha_1, \ldots, \alpha_m)$ , *deg*  $\alpha_l < dct \mathbf{P}_l$  such that

 $\mathbf{F} = \alpha_1 \cdot \mathbf{P}_1 + \ldots + \alpha_m \cdot \mathbf{P}_m.$ 

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#### Also called Sigma Bases or Minimal Approximant Bases

### Sigma Bases (cont.)

An order basis  $\mathbf{P}_1, \ldots, \mathbf{P}_m$  is linearly independent with respect to polynomial coefficients - i.e. a basis of the order module.

Moreover, in terms of vector spaces, we have

$$\mathcal{L}^{\sigma} = \operatorname{span}\{z^{j} \cdot \mathbf{P}_{l} : 1 \leq l \leq m, 0 \leq j < \operatorname{dct} \mathbf{P}_{l}\}$$

 $\dim \mathcal{L}^{\sigma} = \max \{ \det \mathbf{P}_1, 0 \} + \ldots + \max \{ \det \mathbf{P}_m, 0 \}.$ 

### The Sigma Basis Algorithm

Constructive process:

Start with  $\sigma = 0$ .  $\mathbf{P} = I_m$ .  $\mathbf{AP} = z^{\sigma} \mathbf{R}$ .

At each step do:

- If each  $\mathbf{R}_{\ell}(0) = 0$  then increment  $\sigma$
- If there Rℓ(0) ≠ 0 then find pivot and eliminate rest of initial values
- > Pivot should be first column having maximal defect.
- Multiply pivot column by z.

#### The Algorithm

INPUT:  $m \geq 2, s \in \mathbb{N}, \mathbf{A} = (a_1, \dots, a_m)^T$ , multi-index  $\mathbf{n} = (n_1, \dots, n_m)$ INITIALIZATION: Let  $\sigma = 0$ ,  $d_{l,0} = n_l$ ,  $\mathbf{P}_{l,0} = (0, ..., 0, 1, 0, ..., 0)$ RECURSIVE STEP: For  $\sigma = 0, 1, 2, ...$ : Let  $l = 1, \ldots, m$ :  $c_{l,\sigma} = z^{-\sigma} \cdot \mathbf{P}_{l,\sigma}(z^s) \cdot \mathbf{A}(z) \mid_{z=0}$  and  $\Lambda_{\sigma} = \{l : c_{l,\sigma} \neq 0\}$ CASE  $\Lambda_{\sigma} = \{\}$ , then for  $l = 1, \ldots, m$ :  $\mathbf{P}_{l,\sigma+1} = \mathbf{P}_{l,\sigma}, d_{l,\sigma+1} = d_{l,\sigma}$ CASE  $\Lambda_{\sigma} \neq \{\}$ , then let  $\pi = \pi_{\sigma} \in \Lambda_{\sigma}$  be defined by  $d_{\pi,\sigma} = \max\{d_{l,\sigma} : l \in \Lambda_{\sigma}\}$ and compute for  $l = 1, \ldots, m$ :  $l \in \Lambda_{\sigma}, l \neq \pi$ :  $\mathbf{P}_{l,\sigma+1} = \mathbf{P}_{l,\sigma} - \frac{c_{l,\sigma}}{c_{n-\sigma}} \cdot \mathbf{P}_{\pi,\sigma}$ ,  $d_{l,\sigma+1} = d_{l,\sigma}$  $l \notin \Lambda_{\sigma}$ :  $\mathbf{P}_{l,\sigma+1} = \mathbf{P}_{l,\sigma}$ ,  $d_{l,\sigma+1} = d_{l,\sigma}$  $l = \pi$ :  $\mathbf{P}_{\pi,\sigma+1} = z \cdot \mathbf{P}_{\pi,\sigma}$ ,  $d_{\pi,\sigma+1} = d_{\pi,\sigma} - 1$ OUTPUT:  $\sigma$ -bases  $\mathbf{P}_{1,\sigma}, \ldots, \mathbf{P}_{m,\sigma}$  with  $dct \mathbf{P}_{l,\sigma} = d_{l,\sigma} + 1, 1 \leq l \leq m$ .

## Complexity

#### Complexity of Sigma Bases Algorithm

(Complexity : I) For computing vector HPA's of order  $\sigma=0,1,\ldots,\|{\bf n}\|$  :

$$4(m-s) \cdot \|\mathbf{n}\|^2 + \mathcal{O}(m^2 \cdot \|\mathbf{n}\|)$$

roughly half additions and half multiplications plus  $O(m \cdot ||\mathbf{n}||)$  divisions.

(Complexity : II) For the case  $\mathbf{n} = (n, ..., n)$ , we obtain the sharper bound

$$(1-\frac{s}{m})\cdot(2m-\operatorname{card} L)\cdot\|\mathbf{n}\|^2+\mathcal{O}(m^2\cdot\|\mathbf{n}\|)$$

where  $L = \{l : a_l(z) = z^j \text{ with } a_j \in \mathbb{N}_0\}.$ 

#### Faster Sigma Bases Algorithm

**Recursive Computation :** Suppose  $0 \le \rho \le \sigma$  and  $(\mathbf{P}^{(1)}, \mathbf{d}^{(1)}) \longleftarrow FPHPS(\mathbf{A}, \rho, \mathbf{n})$ Let  $\mathbf{A}^{(1)}(z) := z^{-\rho} \cdot \mathbf{P}^{(1)}(z^{s}) \cdot \mathbf{A}(z)$ . Compute  $(\mathbf{P}^{(2)}, \mathbf{d}^{(2)}) \longleftarrow FPHPS(\mathbf{A}^{(1)}, \sigma - \rho, \mathbf{d}^{(1)}).$ Then  $(\mathbf{P}^{(3)}, \mathbf{d}^{(3)}) \leftarrow FPHPS(\mathbf{A}, \sigma, \mathbf{n})$  where 

$$\mathbf{P}^{(3)} = \mathbf{P}^{(2)} \cdot \mathbf{P}^{(1)}$$
 and  $\mathbf{d}^{(3)} = \mathbf{d}^{(2)}$ .

(Complexity) The superfast algorithm for computing vector HPA's of order  $\sigma$  has a complexity of at most

$$\frac{3}{2} \cdot (m+s) \cdot m \cdot \sigma \cdot \log^2 \sigma + \mathcal{O}(\sigma \cdot \log \sigma)$$

roughly half multipications as additions.