

Exercises: Factorization, reduction and decomposition problems

Alban Quadrat*

Exercise 1 Let A be a domain, α an injective endomorphism of A , $D = A[\partial; \alpha, \beta]$ a skew polynomial ring, $E \in A^{n \times n}$ and $F \in A^{n \times n}$, $R = \partial I_n - E \in D^{n \times n}$ and $R' = \partial I_n - F$ two matrices with entries in D , $M = D^{1 \times n} / (D^{1 \times n} R)$ and $M' = D^{1 \times n} / (D^{1 \times n} R')$ two left D -modules respectively finitely presented by R and R' .

1. Describe the left D -modules M and M' in terms of generators and relations.
2. Prove that any $f \in \text{hom}_D(M, M')$ can be defined by means of a matrix $P \in A^{n \times n}$ satisfying the relation $RP = QR'$.
3. Deduce that $Q \in A^{n \times n}$ and prove that $RP = QR'$ is then equivalent to:

$$\begin{cases} Q = \alpha(P), \\ \beta(P) = EP - \alpha(P)F. \end{cases} \quad (1)$$

If $F = E$, then the ring $\mathcal{E} = \{P \in A^{n \times n} \mid \beta(P) = EP - \alpha(P)F\}$ is called the *eigenring*¹ of the linear system:

$$\partial y = Ey.$$

4. Let \mathcal{F} be a left D -module and $\eta \in \ker_{\mathcal{F}}(R')$, i.e., $(\partial I_n - F)\eta = 0$. Then, prove that $\bar{\eta} = P\eta \in \ker_{\mathcal{F}}(R)$, i.e., $(\partial I_n - E)\bar{\eta} = 0$.
5. If $\alpha(P)$ is an invertible matrix, i.e., $\alpha(P) \in \text{GL}_n(A)$, then (1) is equivalent to:

$$F = \alpha(P)^{-1}EP - \alpha(P)^{-1}\beta(P).$$

If $P \in \text{GL}_n(A)$ and $S = P^{-1}$, then prove that (1) is equivalent to:

$$F = \alpha(S)ES^{-1} + \beta(S)S^{-1}.$$

6. Simplify (1) in the case of a skew polynomial ring $D = A[\partial; \alpha, 0]$ of shift operators.
7. Simplify (1) in the case of $D = A[\partial; \text{id}, \frac{d}{dt}]$. We now suppose that A is a field. Taking $F = E$ and using the following identities of the trace,

$$\text{tr}(P_1 + P_2) = \text{tr}(P_1) + \text{tr}(P_2), \quad \text{tr}(P_1 P_2) = \text{tr}(P_2 P_1),$$

*INRIA Sophia Antipolis, 2004, Route des Lucioles, BP 93, 06902 Sophia Antipolis cedex, France.
Alban.Quadrat@sophia.inria.fr, <http://www-sop.inria.fr/members/Alban.Quadrat/index.html>

¹M. F. Singer, "Testing reducibility of linear differential operators: a group theoretic perspective", *Appl. Algebra Engrg. Comm. Comput.*, 7 (1996), 77-104.

prove:

$$\forall P \in \mathcal{E}, \quad \forall k \in \mathbb{N}, \quad \frac{d \operatorname{tr}(P^k)}{dt} = 0.$$

Since the coefficients of the characteristic polynomial $p(\lambda) = \det(\lambda I_n - P)$ are symmetric functions of the eigenvalues of P , prove that they are constant, i.e., they are first integrals of the linear OD system $\partial y = E y$.

8. Consider the integral domain $A = \mathbb{Q}[t]$ and the following matrix:

$$E = \begin{pmatrix} t(2t+1) & -2t^3 - 2t^2 + 1 \\ 2t & -t(2t+1) \end{pmatrix} \in \mathbb{Q}[t]^{2 \times 2}.$$

Let us suppose that the eigenring of $\partial \eta = E \eta$ is defined by:

$$\mathcal{E} = \left\{ P = \begin{pmatrix} a_1 - a_2(t+1) & a_2 t(t+1) \\ -a_2 & a_2 t + a_1 \end{pmatrix} \mid a_1, a_2 \in \mathbb{Q} \right\}.$$

Compute the characteristic polynomial of a generic element P of \mathcal{E} and show that its eigenvalues are constant. Then, compute a Jordan form $J = U^{-1} P U$ of P and prove that $\bar{\eta} = U^{-1} \eta$ satisfies the following linear OD system:

$$\dot{\bar{\eta}} = \begin{pmatrix} -t & 0 \\ 0 & t \end{pmatrix} \bar{\eta}.$$

Finally, integrating this last linear OD system, determine the solution η of $\partial \eta = E \eta$.

9. Let $\mathbb{Q}\{u\}$ be the differential ring formed by differential polynomials in u , namely, polynomials in a finite number of derivatives of u with respect to x and t and

$$\mathfrak{p} = \left\{ \frac{\partial u}{\partial t} - 6u \left(\frac{\partial u}{\partial x} \right) + \frac{\partial^3 u}{\partial x^3} \right\}$$

a prime differential ideal of $\mathbb{Q}\{u\}$, $L = \mathbb{Q}\{u\}/\mathfrak{p}$ the differential ring and

$$K = \{n/d \mid 0 \neq d, n \in L\}$$

its quotient field, i.e., the differential field defined by the *Korteweg-de Vries (KdV) equation*:

$$\frac{\partial u}{\partial t} - 6u \left(\frac{\partial u}{\partial x} \right) + \frac{\partial^3 u}{\partial x^3} = 0. \quad (2)$$

Let us also consider the rings of PD operators $A = K[\partial_x; \operatorname{id}, \frac{\partial}{\partial x}]$ and $D = A[\partial_t; \operatorname{id}, \frac{\partial}{\partial t}]$, the two following PD operators

$$\begin{cases} E = -4\partial_x^3 + 6u\partial_x + 3\left(\frac{\partial u}{\partial x}\right) \in A, \\ R = \partial_t - E \in D, \end{cases}$$

and the finitely presented left D -module $M = D/(DR)$. Prove that the Schrödinger operator $P = -\partial_x^2 + u$ with the potential u satisfies

$$RP - PR = \partial_t P - EP + PE = \frac{\partial u}{\partial t} - 6u \left(\frac{\partial u}{\partial x} \right) + \frac{\partial^3 u}{\partial x^3} = 0,$$

i.e., P defines $f \in \text{end}_D(M)$. In the inverse scattering theory, the last result implies that the smooth one-parameter family of differential operators $t \mapsto -\partial_x^2 + u(x, t)$ defines an *isospectral flow* on the solutions of the evolution equation $\partial_t \eta = E \eta$, namely, if $\psi(x)$ is an eigenvector of the differential operator $-\partial_x^2 + u(x, 0)$ with eigenvalue λ , then the solution $\eta(x, t)$ of the equation $\partial_t \eta(x, t) = E \eta(x, t)$ with the initial value $\eta(x, 0) = \psi(x)$ is an eigenvector of the differential operator $-\partial_x^2 + u(x, t)$ with the same eigenvalue λ .

Exercise 2 Let us consider the linear OD time-delay system

$$\begin{cases} y_1(t - 2h) + y_2(t) - 2\dot{u}(t - h) = 0, \\ y_1(t) + y_2(t - 2h) - 2\dot{u}(t - h) = 0, \end{cases} \quad (3)$$

describing a model of a tank containing a fluid and subjected to a one-dimensional horizontal (F. Dubois, N. Petit, P. Rouchon, “Motion planning and nonlinear simulations for a tank containing a fluid”, in the proceedings of the 5th *European Control Conference*, Karlsruhe (Germany), 1999.). Let $D = \mathbb{Q}[\partial; \text{id}, \frac{d}{dt}][\delta; \alpha, 0]$ be the commutative polynomial ring of OD time-delay operators with rational coefficients (i.e., $\alpha(y(t)) = y(t - h)$), the presentation matrix of (3)

$$R = \begin{pmatrix} \delta^2 & 1 & -2\partial\delta \\ 1 & \delta^2 & -2\partial\delta \end{pmatrix} \in D^{2 \times 3}. \quad (4)$$

and the corresponding finitely presented D -module $M = D^{1 \times 3}/(D^{1 \times 2} R)$.

1. Using the command MORPHISMSCONSTCOEFF of the package ORE Morphisms, find a family of generators $\{f_i\}_{i=1, \dots, r}$ of the D -module $\text{end}_D(M)$ and their D -relations.
2. If $g_1, \dots, g_s \in \text{end}_D(M)$ and $p \in D[x_1, \dots, x_s]$, show that $p(f_1, \dots, f_r)$ can be expressed as a D -linear combination of the f_i 's. Deduce that we only need to know the expressions of the products $f_j \circ f_i$ in terms of the f_k 's (multiplication table) to compute $p(f_1, \dots, f_r)$.
3. Add a third argument to the command MORPHISMSCONSTCOEFF to get the previous multiplication table and the “structure polynomials”.
4. Give a description of $\text{end}_D(M)$ as a quotient of a free associative D -algebra by a certain two-sided ideal. Do the generators of this ideal form a noncommutative Gröbner basis for the total order?

Exercise 3 We consider the so-called *conjugated Beltrami equation* with $\sigma(x, y) = x$:

$$\begin{cases} \frac{\partial z_1(x, y)}{\partial x} - x \frac{\partial z_2(x, y)}{\partial y} = 0, \\ \frac{\partial z_1(x, y)}{\partial y} + x \frac{\partial z_2(x, y)}{\partial x} = 0. \end{cases} \quad (5)$$

Let $D = A_2(\mathbb{Q}) = \mathbb{Q}[x, y][\partial_x; \text{id}, \frac{\partial}{\partial x}][\partial_y; \text{id}, \frac{\partial}{\partial y}]$ be the first Weyl algebra over \mathbb{Q} ,

$$R = \begin{pmatrix} \partial_x & -x \partial_y \\ \partial_y & x \partial_x \end{pmatrix} \in D^{2 \times 2}$$

the presentation matrix of (5) and the left D -module $M = D^{1 \times 2}/(D^{1 \times 2} R)$.

1. Using the command DIMENSION of OREMODULES, compute $\dim_D(M)$. Deduce that M is an infinite-dimensional \mathbb{Q} -vector space.
2. Let $E = B_2(\mathbb{Q}) = \mathbb{Q}[x, y] \left[\frac{\partial}{\partial x}; \text{id}, \frac{\partial}{\partial x} \right] \left[\frac{\partial}{\partial y}; \text{id}, \frac{\partial}{\partial y} \right]$ be the second Weyl algebra over \mathbb{Q} . Compute $\dim_E(E \otimes_D M)$ using the command DIMENSIONRAT.
3. Using the Maple command `pdsolve`, compute one explicit solution of (5).
4. Write this solution under the form of a column vector Z and using the command APPLYMATRIX of OREMODULES, check again that Z satisfies $RZ = 0$.
5. Using the command MORPHISMS of the package ORE Morphisms, compute $\text{end}_D(M)_{(0,0)}$, $\text{end}_D(M)_{(1,0)}$, $\text{end}_D(M)_{(0,1)}$, $\text{end}_D(M)_{(1,1)}$ and $\text{end}_D(M)_{(2,2)}$.
6. For each case, show that we can obtain a new solution of (5) by considering the new vector $Z_{(i,j)} = P_{(i,j)} Z$, where $P_{(i,j)}$ denotes the first output of $\text{end}_D(M)_{(i,j)}$.

Exercise 4 Let A be a differential domain, $D = A \left[\frac{d}{dt}; \text{id}, \frac{d}{dt} \right]$ the skew polynomial ring of OD operators with coefficients in A , $E \in A^{n \times n}$, $R = \partial I_n - E \in D^{n \times n}$ and $M = D^{1 \times n} / (D^{1 \times n} R)$.

1. Compute the formal adjoint \tilde{R} of R .
2. Let $\tilde{N} = D^{1 \times n} / (D^{1 \times n} \tilde{N})$ be the adjoint left D -module of M . Using Exercise 1, prove that any $f \in \text{hom}_D(\tilde{N}, M)$ can be defined by $P \in A^{n \times n}$ satisfying the Lyapunov equation:

$$\frac{dP}{dt} + E^T P + P E = 0.$$

3. Let \mathcal{F} be a left D -module, $\ker_{\mathcal{F}}(R.)$ and $\eta \in \ker_{\mathcal{F}}(R.)$. Considering the quadratic form $V = \eta^T P \eta$, prove that $\frac{dV}{dt} = 0$, i.e., V is a quadratic first integral of $\ker_{\mathcal{F}}(R.)$.
4. Compute a generic quadratic first integral of the linear OD system $\ker_{\mathcal{F}}(R.)$, where

$$E = \begin{pmatrix} 0 & 1 & 0 & 0 \\ -\omega^2 & 0 & \alpha & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & -\omega^2 & \alpha \end{pmatrix} \in \mathbb{Q}(\omega, \alpha)^{4 \times 4},$$

where ω and α are two real constants and $\mathcal{F} = C^\infty(\mathbb{R}_+)$.

Exercise 5 The purpose of this exercise is to study by algebraic means the quadratic first integrals of the following simple mechanical system $\ddot{x}(t) + \alpha \dot{x}(t) + \beta x(t) = 0$, where α and β are two real parameters. Let $D = \mathbb{Q}(\alpha, \beta) \left[\frac{d}{dt}; \text{id}, \frac{d}{dt} \right]$, $R = (\partial^2 + \alpha \partial + \beta)$ and $M = D / (D R)$.

1. Compute the formal adjoint \tilde{R} of R and prove the following identity:

$$\lambda(Rx) = (\tilde{R}\lambda)x + \frac{d}{dt}(\lambda \dot{x} - (\dot{\lambda} - \alpha \lambda)x). \quad (6)$$

2. Let $\tilde{N} = D / (D \tilde{R})$. Using the commutativity of D and

$$\text{gcd}(\partial^2 - \alpha \partial + \beta, \partial^2 + \alpha \partial + \beta) = \begin{cases} 1, & \text{if } \alpha \neq 0, \beta \neq 0, \\ \partial, & \text{if } \alpha \neq 0, \beta = 0, \\ \partial^2 + \beta, & \text{if } \alpha = 0, \end{cases}$$

prove that $f \in \text{hom}_D(\tilde{N}, M)$ can be defined by:

$$(P \quad -Q) = \begin{cases} T(R \quad -\tilde{R}), & T \in D, & \text{if } \alpha \neq 0, \beta \neq 0, \\ T(\partial + \alpha \quad \partial - \alpha), & T \in D, & \text{if } \alpha \neq 0, \beta = 0, \\ T(1 \quad -1), & T \in D, & \text{if } \alpha = 0. \end{cases}$$

3. If $\mathcal{F} = C^\infty(\mathbb{R}_+)$ and $x \in \ker_{\mathcal{F}}(R.)$, then show that

$$\lambda = \begin{cases} Rx = 0, & \text{if } \alpha \neq 0, \beta \neq 0, \\ T(\dot{x} + \alpha x), & T \in D, & \text{if } \alpha \neq 0, \beta = 0, \\ Tx, & T \in D, & \text{if } \alpha = 0, \end{cases}$$

is an element of $\ker_{\mathcal{F}}(\tilde{R}.)$ and, using (6), prove that

$$V(x) = \begin{cases} 0, & \text{if } \alpha \neq 0, \beta \neq 0, \\ (T(\dot{x} + \alpha x))\dot{x} - (T(\ddot{x} + \alpha\dot{x} - \alpha(\dot{x} + \alpha x)))x = T(\dot{x} + \alpha x)^2, & \text{if } \alpha \neq 0, \beta = 0, \\ (Tx)\dot{x} - (T\dot{x})x, & \text{if } \alpha = 0, \end{cases}$$

are quadratic first integrals of $\ker_{\mathcal{F}}(\tilde{R}.)$.

4. In the last case, since the system is a second order ODE, we can take $T = a_1 \partial + a_2$, where $a_1, a_2 \in \mathbb{Q}(\beta, m)$. Prove that we get the following first integral of $\ker_{\mathcal{F}}(R.)$:

$$V(x) = (a_1 \dot{x} + a_2 x)\dot{x} + (-a_1 \ddot{x} - a_2 \dot{x})x = a_1 (\dot{x}^2 + \beta x^2).$$

Exercise 6 The movement of an incompressible fluid rotating with a small velocity around the axis lying along the x_3 axis can be defined by

$$\begin{cases} \rho_0 \frac{\partial u_1}{\partial t} - 2\rho_0 \Omega_0 u_2 + \frac{\partial p}{\partial x_1} = 0, \\ \rho_0 \frac{\partial u_2}{\partial t} + 2\rho_0 \Omega_0 u_1 + \frac{\partial p}{\partial x_2} = 0, \\ \rho_0 \frac{\partial u_3}{\partial t} + \frac{\partial p}{\partial x_3} = 0, \\ \frac{\partial u_1}{\partial x_1} + \frac{\partial u_2}{\partial x_2} + \frac{\partial u_3}{\partial x_3} = 0, \end{cases} \quad (7)$$

where $u = (u_1, u_2, u_3)^T$ denotes the local rate of velocity, p the pressure, ρ_0 the constant fluid density and Ω_0 the constant angle speed.

Let $D = \mathbb{Q}(\rho_0, \Omega_0) [\partial_t; \text{id}, \frac{\partial}{\partial t}] [\partial_1; \text{id}, \frac{\partial}{\partial x_1}] [\partial_2; \text{id}, \frac{\partial}{\partial x_2}] [\partial_3; \text{id}, \frac{\partial}{\partial x_3}]$ be the commutative polynomial ring of differential operators,

$$R = \begin{pmatrix} \rho_0 \partial_t & -2\rho_0 \Omega_0 & 0 & \partial_1 \\ 2\rho_0 \Omega_0 & \rho_0 \partial_t & 0 & \partial_2 \\ 0 & 0 & \rho_0 \partial_t & \partial_3 \\ \partial_1 & \partial_2 & \partial_3 & 0 \end{pmatrix} \in D^{4 \times 4}$$

the presentation matrix of (7) and the D -module $M = D^{1 \times 4} / (D^{1 \times 4} R)$ associated with (7).

1. Compute the formal adjoint \tilde{R} of R . What is the relation between R and \tilde{R} .
2. If we denote by $\eta = (u_1 \ u_2 \ u_2 \ p)^T$, then check the following identity:

$$(\lambda, R\eta) = (\eta, \tilde{R}\lambda) + (\partial_t \ \partial_1 \ \partial_2 \ \partial_3) \begin{pmatrix} \rho_0 (\lambda_1 u_1 + \lambda_2 u_2 + \lambda_3 u_3) \\ \lambda_1 p + \lambda_4 u_1 \\ \lambda_2 p + \lambda_4 u_2 \\ \lambda_3 p + \lambda_4 u_3 \end{pmatrix}.$$

3. Compare $\tilde{N} = D^{1 \times 4} / (D^{1 \times 4} \tilde{R})$ and $M = D^{1 \times 4} / (D^{1 \times 4} R)$. Compare $\text{hom}_D(\tilde{N}, M)$ and $\text{end}_D(M)$. What are the simplest elements of $\text{hom}_D(\tilde{N}, M)$?
4. If (\vec{u}, p) is a solution of (7), then find a simple solution of $\tilde{R}\lambda = 0$ and prove that (7) admits the following quadratic conservation law:

$$\begin{aligned} \partial_t (\rho_0 (u_1^2 + u_2^2 + u_3^2)) + \partial_1 (2p u_1) + \partial_2 (2p u_2) + \partial_3 (2p u_3) &= 0, \\ \Leftrightarrow \partial_t \left(\frac{\rho_0}{2} \|\vec{u}\|^2 \right) + \vec{\nabla} \cdot (p\vec{u}) &= 0. \end{aligned}$$

Exercise 7 Let $D = \mathbb{Z}$, $R = 4$, $M = D / (DR) = \mathbb{Z} / (4\mathbb{Z})$ and $f \in \text{end}_D(M)$ defined by $f(m) = 2m$, for all $m \in M$.

1. Find a finite free resolution of the D -module M .
2. Compute $\text{coker } f$ and $\text{ker } f$.
3. Deduce a free resolution of $\mathbb{Z}_2 = \mathbb{Z} / (2\mathbb{Z})$ as $\mathbb{Z} / (4\mathbb{Z})$ -module. Conclude on its length and on the projective dimension of $\mathbb{Z}_2 = \mathbb{Z} / (2\mathbb{Z})$ as $\mathbb{Z} / (4\mathbb{Z})$ -module.

Exercise 8 Let us consider the so-called *Oseen equations* defined by

$$\begin{cases} -\nu \Delta \vec{u} + (\vec{b} \cdot \vec{\nabla}) \vec{u} + c \vec{u} + \vec{\nabla} p = 0, \\ \vec{\nabla} \cdot \vec{u} = 0, \end{cases} \quad (8)$$

where \vec{u} denotes the velocity, p the pressure, ν the viscosity and \vec{b} a steady velocity and c a constant reaction coefficient, which describe the flow of a viscous and incompressible fluid at small Reynolds numbers (linearization of the incompressible Navier-Stokes equations at a steady state). Let $D = \mathbb{Q}(\nu, b_1, b_2, c) \left[\partial_x; \text{id}, \frac{\partial}{\partial x} \right] \left[\partial_y; \text{id}, \frac{\partial}{\partial y} \right]$ be the ring of PD operators with coefficients in the field $\mathbb{Q}(\nu, b_1, b_2, c)$, the presentation matrix of (8)

$$R = \begin{pmatrix} -\nu \Delta + b_1 \partial_x + b_2 \partial_y + c & 0 & \partial_x \\ 0 & -\nu \Delta + b_1 \partial_x + b_2 \partial_y + c & \partial_y \\ \partial_x & \partial_y & 0 \end{pmatrix} \in D^{3 \times 3},$$

and the finitely presented D -module $M = D^{1 \times 3} / (D^{1 \times 3} R)$.

1. Check that $P = Q = \Delta I_3$ defines a D -endomorphism f_1 of M , where $\Delta = \partial_x^2 + \partial_y^2$.
2. Compute $\text{ker } f_1$. Is f_1 injective? You can use the command `TESTINJ` of `OREMORPHISMS`. If not, compute a factorization $R = L_1 S_1$ of R .

3. Find directly the matrix S_1 using the command `COIMMORPHISM` of `OREMORPHISMS`.
4. Check that $P = Q = (\nu \Delta - b_1 \partial_x - b_2 \partial_y - c) I_3$ defines a D -endomorphism f_2 of M .
5. Compute $\ker f_2$. Is f_2 injective? If not, compute a factorization $R = L_2 S_2$ of R .
6. Find directly the matrix S_2 using the command `COIMMORPHISM` of `OREMORPHISMS`.

Exercise 9 Let $D = \mathbb{Q}[\partial; \text{id}, \frac{d}{dt}]$, $R = (\partial - 1)$, $R' = (\partial^2 - 1)$ and $M = D^{1 \times 2}/(DR)$ and $M' = D^{1 \times 2}/(DR')$ two D -modules which, in terms of generators and relations, are respectively defined by $\partial x = u$ and $\partial^2 y = v$. Using the commands `MORPHISMSCONSTCOEFF` and `TESTISO` of `OREMORPHISMS`, prove that $M \cong M'$. In particular, compute an isomorphism $f : M \rightarrow M'$ and its inverse f^{-1} .

Exercise 10 Using the commands `MORPHISMSCONSTCOEFF` and `TESTISO` of `OREMORPHISMS`, prove that the following systems are equivalent:

$$\left\{ \begin{array}{l} \partial_1 \xi_1 = 0, \\ \frac{1}{2} (\partial_2 \xi_1 + \partial_1 \xi_2) = 0, \\ \partial_2 \xi_2 = 0, \end{array} \right. \quad \left\{ \begin{array}{l} \partial_1 \zeta_1 = 0, \\ \partial_2 \zeta_1 - \zeta_2 = 0, \\ \partial_1 \zeta_2 = 0, \\ \partial_1 \zeta_3 + \zeta_2 = 0, \\ \partial_2 \zeta_3 = 0, \\ \partial_2 \zeta_2 = 0. \end{array} \right.$$

In particular, exhibit an explicit isomorphism between the two underlying differential modules and its inverse.

Exercise 11 Let $D = A_1(\mathbb{Q})$ be the first Weyl algebra, R the following matrix:

$$R = \begin{pmatrix} \partial & -t & t & \partial \\ \partial & t\partial - t & \partial & -1 \\ \partial & -t & \partial + t & \partial - 1 \\ \partial & \partial - t & t & \partial \end{pmatrix} \in D^{4 \times 4},$$

and $M = D^{1 \times 4}/(D^{1 \times 4}R)$ the left D -module finitely presented by R .

1. Using the command `MORPHISMS` of `OREMORPHISMS`, compute $\text{end}_D(M)_{(0,0)}$.
2. Check if the generic element P obtained in 1 admits a non-trivial left kernel.
3. Compute the determinant of P and deduce values of the arbitrary parameters for which P becomes singular. Compute the corresponding Q 's.
4. For each of those values:
 - (a) Check that the left D -modules $\ker_D(.P)$, $\text{coim}_D(.P)$, $\ker_D(.Q)$ and $\text{coim}_D(.Q)$ are free and compute a basis for each of them. Denote the corresponding matrices respectively by U_1, U_2, V_1 and V_2 .
 - (b) Form the matrices $U = (U_1^T \ U_2^T)^T \in D^{4 \times 4}$ and $V = (V_1^T \ V_2^T)^T \in D^{4 \times 4}$ and check that $U \in \text{GL}_4(D)$ and $V \in \text{GL}_4(D)$.

- (c) Conclude that R is equivalent to the block-triangular matrix $\bar{R} = V R U^{-1}$.
(d) Check this last result using HEURISTICREDUCTION.

Exercise 12 Let us consider the following four complex matrices:

$$\gamma^1 = \begin{pmatrix} 0 & 0 & 0 & -i \\ 0 & 0 & -i & 0 \\ 0 & i & 0 & 0 \\ i & 0 & 0 & 0 \end{pmatrix}, \quad \gamma^2 = \begin{pmatrix} 0 & 0 & 0 & -1 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ -1 & 0 & 0 & 0 \end{pmatrix},$$

$$\gamma^3 = \begin{pmatrix} 0 & 0 & -i & 0 \\ 0 & 0 & 0 & i \\ i & 0 & 0 & 0 \\ 0 & -i & 0 & 0 \end{pmatrix}, \quad \gamma^4 = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 \end{pmatrix}.$$

The Dirac equation for a massless particle has the form

$$\sum_{j=1}^4 \gamma^j \frac{\partial \psi(x)}{\partial x_j} = 0, \quad (9)$$

where $\psi = (\psi_1 \ \psi_2 \ \psi_3 \ \psi_4)^T$ and $x = (x_1, x_2, x_3, x_4)$ are the space-time coordinates.

Let $D = \mathbb{Q}(i) \left[\partial_1; \text{id}, \frac{\partial}{\partial x_1} \right] \left[\partial_2; \text{id}, \frac{\partial}{\partial x_2} \right] \left[\partial_3; \text{id}, \frac{\partial}{\partial x_3} \right] \left[\partial_4; \text{id}, \frac{\partial}{\partial x_4} \right]$ be the commutative polynomial ring of PD operators ($\partial_4 = -i \partial_t$),

$$R = \begin{pmatrix} \partial_4 & 0 & -i \partial_3 & -(i \partial_1 + \partial_2) \\ 0 & \partial_4 & -i \partial_1 + \partial_2 & i \partial_3 \\ i \partial_3 & i \partial_1 + \partial_2 & -\partial_4 & 0 \\ i \partial_1 - \partial_2 & -i \partial_3 & 0 & -\partial_4 \end{pmatrix} \in D^{4 \times 4}$$

the presentation matrix of (9) and the finitely presented D -module $M = D^{1 \times 4} / (D^{1 \times 4} R)$.

Redo Exercise 11 with the ring D and the matrix R .

Exercise 13 We consider the following linear PD system

$$\sigma \partial_t \vec{A} + \frac{1}{\mu} \vec{\nabla} \wedge \vec{\nabla} \vec{A} - \sigma \vec{\nabla} V = 0,$$

where (\vec{A}, V) denotes the electromagnetic quadri-potential, σ the electric conductivity and μ the magnetic permeability. It corresponds to the equations satisfied by quadri-potential (\vec{A}, V) when it is assumed that the term $\partial_t \vec{D}$ can be neglected in the Maxwell equations, i.e., the electric displacement \vec{D} is constant in time. It seems that Maxwell was led to introduce the term $\partial_t \vec{D}$ in his famous equations for pure mathematical reasons.

Redo Exercise 12 with now $D = \mathbb{Q} \left[\partial_t; \text{id}, \frac{\partial}{\partial t} \right] \left[\partial_1; \text{id}, \frac{\partial}{\partial x_1} \right] \left[\partial_2; \text{id}, \frac{\partial}{\partial x_2} \right] \left[\partial_3; \text{id}, \frac{\partial}{\partial x_3} \right]$ and the following matrices:

$$R = \frac{1}{\mu} \begin{pmatrix} \sigma \mu \partial_t - (\partial_2^2 + \partial_3^2) & \partial_1 \partial_2 & \partial_1 \partial_3 & -\sigma \mu \partial_1 \\ \partial_1 \partial_2 & \sigma \mu \partial_t - (\partial_1^2 + \partial_3^2) & \partial_2 \partial_3 & -\sigma \mu \partial_2 \\ \partial_1 \partial_3 & \partial_2 \partial_3 & \sigma \mu \partial_t - (\partial_1^2 + \partial_2^2) & -\sigma \mu \partial_3 \end{pmatrix},$$

$$P = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & \sigma \mu \partial_t & 0 & -\sigma \mu \partial_2 \\ 0 & 0 & \sigma \mu \partial_t & -\sigma \mu \partial_3 \\ 0 & \partial_t \partial_2 & \partial_t \partial_3 & -(\partial_2^2 + \partial_3^2) \end{pmatrix}, \quad Q = \begin{pmatrix} 0 & 0 & 0 \\ -\partial_1 \partial_2 & \sigma \mu \partial_t - \partial_2^2 & -\partial_2 \partial_3 \\ -\partial_1 \partial_3 & -\partial_2 \partial_3 & \sigma \mu \partial_t - \partial_3^2 \end{pmatrix}.$$

Exercise 14 We consider again Exercise 11 and $f \in \text{end}_D(M)$ defined by the matrices:

$$P = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix} \in \mathbb{Q}^{4 \times 4}, \quad Q = \begin{pmatrix} t+1 & 1 & -1 & -t \\ 1 & 1 & -1 & 0 \\ t+1 & 1 & -1 & -t \\ t & 1 & -1 & -t+1 \end{pmatrix} \in \mathbb{Q}[t]^{4 \times 4}.$$

The purpose of this exercise is to study the decomposition of the left D -module M as

$$M = M_1 \oplus M_2,$$

where M_1 and M_2 are two left D -submodules of M , and integrate this decomposition in terms of linear OD systems.

1. Check that $P^2 = P$ and $Q^2 = Q$. Deduce that $f^2 = f$, i.e., f is an idempotent of $\text{end}_D(M)$.
2. Prove that $g = \text{id}_M - f$ is a left D -homomorphism from M to $\ker f$.
3. If $i : \ker f \rightarrow M$ denotes the canonical injection, then show that $g \circ i = \text{id}_{\ker f}$. Deduce that the following short exact sequence

$$0 \longrightarrow \ker f \xrightarrow{i} M \xrightarrow{\rho} \text{coim } f = M / \ker f \longrightarrow 0$$

splits, i.e., $M \cong \ker f \oplus \text{coim } f$.

4. Prove that $f^\sharp : \text{coim } f \rightarrow M$ defined by $f^\sharp(\rho(m)) = f(m)$ is well-defined by considering two elements m and $m' \in M$ satisfying $\rho(m) = \rho(m')$. Check that $\rho \circ f^\sharp \circ \rho = \rho$, i.e., $f^\sharp \circ \rho = \text{id}_{\text{coim } f}$ and conclude that $M = \ker f \oplus f^\sharp(\text{coim } f)$.
5. Using the command `COIMMORPHISM`, compute a presentation matrix $S \in D^{4 \times 4}$ of $\text{coim } f$, i.e., $\text{coim } f = D^{1 \times 4} / (D^{1 \times 4} S)$.
6. Using the command `FACTORIZE` of `OREMODULES`, compute $L \in D^{4 \times 4}$ satisfying $R = L S$.
7. Using the command `SYZYGYMODULE` of `OREMODULES`, check that $\ker_D(.S) = 0$. Deduce that L is a presentation matrix of the left D -module $\ker f$, i.e., $\ker f \cong D^{1 \times 4} / (D^{1 \times 4} L)$.
8. Using the command `FACTORIZE`, compute $X \in D^{4 \times 4}$ satisfying $P = I_4 - X S$.
9. Using the commands `APPLYMATRIX` of `OREMODULES` and `dsolve` of Maple, compute the solution $S \zeta = 0$.
10. Similarly, compute the solution of $L \tau = 0$.
11. Form $\eta = \zeta + X \tau$ and check that $R \eta = 0$.

Exercise 15 Let $D = \mathbb{Q} [\partial_t; \text{id}, \frac{\partial}{\partial t}] [\partial_x; \text{id}, \frac{\partial}{\partial x}]$ be the commutative polynomial ring of PD operators with rational constant coefficients, $R = (\partial_t - \partial_x \quad \partial_t - \partial_x^2)^T$, $I = D^{1 \times 2} R = (\partial_t - \partial_x, \partial_t - \partial_x^2)$ the ideal of D formed by the transport and the heat operators, the D -module $M = D/I$ and $\pi : D \rightarrow M$ the canonical projection onto M .

1. Prove that $e : M \rightarrow M$ defined by $e(\pi(\lambda)) = \lambda \partial_t$, for all $\lambda \in D$, is a D -endomorphism of M , i.e., $e \in \text{end}_D(M)$. Deduce that e can be defined by $P = \partial_t$, $Q = \partial_t I_2$.
2. Prove that e is an idempotent of the endomorphism ring $E = \text{end}_D(M)$ of M , i.e., $e^2 = e$.
3. Prove that the matrices defined by

$$S = \begin{pmatrix} \partial_t - 1 \\ \partial_x - \partial_t \end{pmatrix}, \quad L = \begin{pmatrix} 0 & -1 \\ -\partial_t & -\partial_t - \partial_x \end{pmatrix}, \quad S_2 = (\partial_x - \partial_t \quad 1 - \partial_t),$$

and $X = (-1 \quad 0)$ satisfy $\text{coim } f = D/(D^{1 \times 2} S)$, $R = L S$, $\ker_D(.S) = D S_2$ and $P = 1 - X S$.

4. Compute the general solution of the linear PD system $S \zeta = 0$.
5. Compute the general solution of the linear PD system $(L^T \quad S_2^T)^T \tau = 0$.
6. Finally, check that $\eta = \zeta + X \tau = c_1 e^{x+t} + c_2$, where c_1 and c_2 are two arbitrary constants, is the general solution of $R \eta = 0$.

Exercise 16 Let $D = \mathbb{Q} [\partial_t; \text{id}, \frac{\partial}{\partial t}] [\partial_x; \text{id}, \frac{\partial}{\partial x}]$ be the commutative polynomial ring of PD operators with rational constant coefficients, $R = (\partial_t^2 - \partial_x^2 \quad \partial_t - \partial_x^2)^T$, $I = D^{1 \times 2} R = (\partial_t - \partial_x, \partial_t - \partial_x^2)$ the ideal of D formed by the wave and the heat operators, the D -module $M = D/I$ and $\pi : D \rightarrow M$ the canonical projection onto M .

1. Prove that $e : M \rightarrow M$ defined by $e(\pi(\lambda)) = \lambda \partial_t$, for all $\lambda \in D$, is a D -endomorphism of M , i.e., $e \in \text{end}_D(M)$. Deduce that e can be defined by $P = \partial_t$, $Q = \partial_t I_2$.
2. Prove that e is an idempotent of the endomorphism ring $E = \text{end}_D(M)$ of M , i.e., $e^2 = e$.
3. Prove that the matrices defined by

$$S = \begin{pmatrix} \partial_t - 1 \\ \partial_x^2 - 1 \\ 0 \end{pmatrix}, \quad L = \begin{pmatrix} \partial_t + 1 & -1 & 0 \\ 1 & -1 & 0 \end{pmatrix}, \quad S_2 = \begin{pmatrix} \partial_x^2 - 1 & -\partial_t + 1 & 0 \\ 0 & 0 & 1 \end{pmatrix},$$

and $X = (-1 \quad 0 \quad 0)$ satisfy $\text{coim } f = D/(D^{1 \times 3} S)$, $R = L S$, $\ker_D(.S) = D^{1 \times 2} S_2$ and $P = 1 - X S$.

4. Let $\mathcal{F} = C^\infty(\mathbb{R}^2)$. Prove that $\ker_{\mathcal{F}}(S) = \{\zeta = c_1 e^{t-x} + c_2 e^{t+x} \mid c_1, c_2 \in \mathbb{R}\}$.
5. Prove $\ker_{\mathcal{F}}((L^T \quad S_2^T)^T) = \{\tau = (c_3 x + c_4 \quad c_3 x + c_4 \quad 0)^T \mid c_3, c_4 \in \mathbb{R}\}$.
6. Finally, deduce that $\ker_{\mathcal{F}}(R) = \{\eta = c_1 e^{t-x} + c_2 e^{t+x} - c_3 x - c_4 \mid c_i \in \mathbb{R}, i = 1, \dots, 4\}$.

Exercise 17 Let $R \in D^{q \times p}$ be a full row rank matrix, i.e., $\ker_D(.R) = 0$, and $P \in D^{p \times p}$, $Q \in D^{q \times q}$ two matrices satisfying the relation $RP = QR$. Prove that if P is an idempotent of $D^{p \times p}$, i.e., $P^2 = P$, then so is Q , i.e., $Q^2 = Q$.

Considering again Exercise 1, prove that an idempotent e of $\text{end}_D(M)$ can always be defined by $P \in A^{n \times n}$ and $Q \in A^{n \times n}$ satisfying $P^2 = P$, i.e., P is an idempotent matrix of $A^{n \times n}$. Conclude that $Q^2 = Q$, i.e., Q is also an idempotent matrix of $A^{n \times n}$.

Exercise 18 Let $R \in D^{q \times p}$ be a full row rank matrix, $M = D^{1 \times p}/(D^{1 \times q}R)$ and $f \in \text{end}_D(M)$ be defined by two matrices $P \in D^{p \times p}$ and $Q \in D^{q \times q}$ satisfying the relations:

$$RP = QR, \quad P^2 = P + ZR, \quad Q^2 = Q + RZ.$$

Prove that if there exists a solution $\Lambda \in D^{p \times q}$ of the following algebraic Riccati equation

$$\Lambda R \Lambda + (P - I_p) \Lambda + \Lambda Q + Z = 0, \quad (10)$$

then the matrices defined by

$$\begin{cases} \bar{P} = P + \Lambda R, \\ \bar{Q} = Q + R \Lambda, \end{cases} \quad (11)$$

satisfy the following relations:

$$R\bar{P} = \bar{Q}R, \quad \bar{P}^2 = \bar{P}, \quad \bar{Q}^2 = \bar{Q}.$$

Exercise 19 We consider $D = A_1(\mathbb{Q})$, $R = (\partial^2 \quad -t\partial - 1)$ and $M = D^{1 \times 2}/(DR)$.

1. Using MORPHISMS, compute the endomorphisms of M defined by matrices P of degree 1 in ∂ and 2 in t .
2. Using the command IDEMPOTENTS of OREMORPHISMS, search for idempotents of $\text{end}_D(M)$ in the previous endomorphisms.
3. For the non trivial ones (i.e., different from 0 and id_M), compute the corresponding matrices Q 's.
4. Compute the matrices $Z \in D^2$ satisfying $P^2 = P + ZR$ and check that the P 's are not idempotents of $D^{2 \times 2}$.
5. Using the command RICCATI of OREMORPHISMS, solve the algebraic Riccati equation (10) for different orders and degrees till you reach non trivial solutions.
6. Using (11), compute the corresponding \bar{P} 's and \bar{Q} 's and check that they are respectively idempotents of $D^{2 \times 2}$ and D .

Exercise 20 We consider again Exercise 14.

1. Using SYZGYMODULE, compute $\ker_D(.P)$ and conclude that $\ker_D(.P)$ is a free left D -module. Denote the corresponding matrix by U_1 .
2. Using SYZGYMODULE, compute $\text{im}_D(.P) = \ker_D(. (I_4 - P))$ and conclude that $\text{im}_D(.P)$ is a free left D -module. Denote the corresponding matrix by U_2 .
3. Similarly:

- (a) Compute $\ker_D(.Q)$ and conclude that $\ker_D(.Q)$ is a free left D -module. Denote the corresponding matrix by V_1 .
 - (b) Compute $\text{im}_D(.Q) = \ker_D(. (I_4 - Q))$ and conclude that $\text{im}_D(.Q)$ is a free left D -module. Denote the corresponding matrix by V_2 .
4. Form the matrices $U = (U_1^T \ U_2^T)^T$ and $V = (V_1^T \ V_2^T)^T$ and show that $U \in \text{GL}_4(D)$ and $V \in \text{GL}_4(D)$.
 5. Check that R is equivalent to the block-diagonal matrix $\bar{R} = V R U^{-1}$ and find again the solution η of the linear OD system $R \eta = 0$ computed in Exercise 14.
 6. Check that last result using the command `HEURISTICDECOMPOSITION`.

Exercise 21 We consider again Exercise 12. Using the methodology explained in Exercise 20, prove that the matrix R is equivalent to the following matrix

$$\bar{R} = V R U^{-1} = \begin{pmatrix} -\partial_4 + i \partial_3 & i \partial_1 + \partial_2 & 0 & 0 \\ i \partial_1 - \partial_2 & -\partial_t - i \partial_3 & 0 & 0 \\ 0 & 0 & \partial_4 + i \partial_3 & i \partial_1 + \partial_2 \\ 0 & 0 & i \partial_1 - \partial_2 & \partial_4 - i \partial_3 \end{pmatrix},$$

where the unimodular matrices U and V are defined by:

$$U = \begin{pmatrix} 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 \\ -1 & 0 & 1 & 0 \\ 0 & -1 & 0 & 1 \end{pmatrix} \in \text{GL}_4(D), \quad V = \begin{pmatrix} -1 & 0 & 1 & 0 \\ 0 & -1 & 0 & 1 \\ -1 & 0 & -1 & 0 \\ 0 & -1 & 0 & -1 \end{pmatrix} \in \text{GL}_4(D).$$

Note that the computations with `OREMORPHISMS` of the set of generators of $\text{end}_D(M)$ and some of its idempotents took me respectively 134 and 18 CPU time on my Mac OS X (Maple 10, 2.8 GHz, 4 GB Ram).

Exercise 22 We consider the Cauchy-Riemann equations defined by:

$$\begin{cases} \frac{\partial u}{\partial x} - \frac{\partial v}{\partial y} = 0, \\ \frac{\partial u}{\partial y} + \frac{\partial v}{\partial x} = 0. \end{cases}$$

Let $D = \mathbb{Q} [\partial_x; \text{id}, \frac{\partial}{\partial x}] [\partial_y; \text{id}, \frac{\partial}{\partial y}]$, $R = \begin{pmatrix} \partial_x & -\partial_y \\ \partial_y & \partial_x \end{pmatrix} \in D^{2 \times 2}$ and $M = D^{1 \times 2} / (D^{1 \times 2} R)$.

1. Using `MORPHISMSCONSTCOEFF`, compute a family of generators of $\text{end}_D(M)$, their relations and the corresponding multiplication table.
2. Using the command `IDEMPOTENTSCONSTCOEFF` of `OREMORPHISMS`, show that the $E = \mathbb{Q}(i) [\partial_x; \text{id}, \frac{\partial}{\partial x}] [\partial_y; \text{id}, \frac{\partial}{\partial y}]$ -module $N = E^{1 \times 2} / (E R)$ is decomposable. Deduce that the matrices P and Q defined by

$$P = Q = \frac{1}{2} \begin{pmatrix} 1 & i \\ -i & 1 \end{pmatrix}$$

satisfy $R P = P R$ and $P^2 = P$, i.e., define an idempotent of $\text{end}_E(M)$.

- Using the command SYZGYMODULE, compute basis of the free E -modules $\ker_E(.P)$ and $\text{im}_E(.P) = \ker_E(.I_2 - P)$.
- Forming the matrix $U = (U_1^T \ U_2^T)^T \in \text{GL}_2(E)$, check that R is then equivalent to the following block-diagonal matrix:

$$\bar{R} = U R U^{-1} = \begin{pmatrix} \partial_x - i \partial_y & 0 \\ 0 & \partial_x + i \partial_y \end{pmatrix} = 2 \begin{pmatrix} \bar{\partial} & 0 \\ 0 & \partial \end{pmatrix},$$

with the following notations:

$$U = \begin{pmatrix} i & 1 \\ i & -1 \end{pmatrix} \in \text{GL}_2(E), \quad \bar{\partial} = \frac{1}{2}(\partial_x - i \partial_y), \quad \partial = \frac{1}{2}(\partial_x + i \partial_y).$$

Exercise 23 We consider a wave equation defined by the following linear PD system:

$$\begin{cases} \frac{\partial y_1}{\partial x} + a \frac{\partial y_2}{\partial t} = 0, \\ \frac{\partial y_1}{\partial t} + b \frac{\partial y_2}{\partial x} = 0. \end{cases}$$

Acoustic wave: $y_1 = u, y_2 = p, a = 1/\rho, b = \rho c^2$.

LC transmission line: $y_1 = v, y_2 = i, a = L, b = 1/C$.

Let $D = \mathbb{Q}(a, b) [\partial_t; \text{id}, \frac{\partial}{\partial t}] [\partial_x; \text{id}, \frac{\partial}{\partial x}]$, $R = \begin{pmatrix} \partial_x & a \partial_t \\ \partial_t & b \partial_x \end{pmatrix} \in D^{2 \times 2}$ and $M = D^{1 \times 2} / (D^{1 \times 2} R)$.

- Using MORPHISMSCONSTCOEFF, compute a family of generators of $\text{end}_D(M)$, their relations and the corresponding multiplication table.
- Using the command IDEMPOTENTSCONSTCOEFF of OREMORPHISMS, show that the $E = \mathbb{Q}(a, b)[\alpha] / (4ab\alpha^2 - 1) [\partial_x; \text{id}, \frac{\partial}{\partial x}] [\partial_y; \text{id}, \frac{\partial}{\partial y}]$ -module $N = E^{1 \times 2} / (E R)$ is decomposable. Deduce that the matrices P and Q defined by

$$P = \frac{1}{2} \begin{pmatrix} 1 & 2ab\alpha \\ 2\alpha & 1 \end{pmatrix}, \quad Q = \frac{1}{2} \begin{pmatrix} 1 & 2a\alpha \\ 2b\alpha & 1 \end{pmatrix},$$

satisfy $RP = PR$ and $P^2 = P$, i.e., define an idempotent of $\text{end}_E(M)$.

- Using the command SYZGYMODULE, compute basis of the free E -modules $\ker_E(.P)$ and $\text{im}_D(.P) = \ker_E(.I_2 - P)$, $\ker_E(.Q)$ and $\text{im}_D(.Q) = \ker_E(.I_2 - Q)$.
- Forming the matrices $U = (U_1^T \ U_2^T)^T \in \text{GL}_2(E)$ and $V = (V_1^T \ V_2^T)^T \in \text{GL}_2(E)$, check that R is then equivalent to the following block-diagonal matrix:

$$\bar{R} = V R U^{-1} = \begin{pmatrix} b \partial_x - \frac{1}{2\alpha} \partial_t & 0 \\ 0 & b \partial_x + \frac{1}{2\alpha} \partial_t \end{pmatrix},$$

with the following notations:

$$U = \begin{pmatrix} -2\alpha & 1 \\ 2\alpha & 1 \end{pmatrix} \in \text{GL}_2(E), \quad V = \begin{pmatrix} -2b\alpha & 1 \\ 2b\alpha & 1 \end{pmatrix} \in \text{GL}_2(E).$$

5. Explain that the previous decomposition proves the D'Alembert theorem stating that the solution of a wave equation can be decomposed into two transport equations with opposite speed directions, i.e., the solution of $(\partial_t^2 - c^2 \partial_x^2) u(t, x) = 0$ can be decomposed as follows:

$$u(t, x) = f(x - \sqrt{c}t) + g(x + \sqrt{c}t).$$

Exercise 24 We consider the linearized approximation of the steady two-dimensional rotational isentropic flow

$$\begin{cases} u \rho \frac{\partial \omega}{\partial x} + c^2 \frac{\partial \sigma}{\partial x} = 0, \\ u \rho \frac{\partial \lambda}{\partial x} + c^2 \frac{\partial \sigma}{\partial y} = 0, \\ \rho \frac{\partial \omega}{\partial x} + \rho \frac{\partial \lambda}{\partial y} + u \frac{\partial \sigma}{\partial x} = 0, \end{cases} \quad (12)$$

where u is a constant velocity parallel to the x -axis, ρ a constant density and c the speed of sound. See R. Courant, D. Hilbert, *Methods of Mathematical Physics*, Wiley Classics Library, Wiley, 1989. Using OREMORPHISMS, prove that if α satisfies $1 + 4(c^2 - u^2)\alpha^2 = 0$ and

$$E = \mathbb{Q}(u, \rho, c)[\alpha]/(1 + 4(c^2 - u^2)\alpha^2) \left[\partial_x; \text{id}, \frac{\partial}{\partial x} \right] \left[\partial_y; \text{id}, \frac{\partial}{\partial y} \right],$$

then the presentation matrix of (12) defined by

$$R = \begin{pmatrix} u \rho \partial_x & c^2 \partial_x & 0 \\ 0 & c^2 \partial_y & u \rho \partial_x \\ \rho \partial_x & u \partial_x & \rho \partial_y \end{pmatrix} \in E^{3 \times 3},$$

is equivalent to the following block-diagonal matrix

$$\bar{R} = V R U^{-1} = \begin{pmatrix} \partial_x - 2\alpha c \partial_y & 0 & 0 \\ 0 & \partial_x + 2\alpha c \partial_y & 0 \\ 0 & 0 & \partial_x \end{pmatrix},$$

where:

$$U = \begin{pmatrix} 0 & 2\alpha c(c^2 - u^2) & u \rho \\ 0 & 2\alpha c(c^2 - u^2) & -u \rho \\ u \rho & c^2 & 0 \end{pmatrix} \in \text{GL}_3(E), \quad V = \begin{pmatrix} 2\alpha c & 1 & -2\alpha c u \\ 2\alpha c & -1 & -2\alpha c u \\ 1 & 0 & 0 \end{pmatrix} \in \text{GL}_3(E).$$

Exercise 25 We consider again Exercise 2.

1. Using the multiplication table, prove that $f = \frac{1}{2}(f_1 + f_2) \in \text{end}_D(M)$, defined by

$$P = \frac{1}{2} \begin{pmatrix} 1 & 1 & 0 \\ 1 & 1 & 0 \\ 0 & 0 & 2 \end{pmatrix}, \quad Q = \frac{1}{2} \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix},$$

is an idempotent $f \in \text{end}_D(M)$. Deduce that M can be decomposed.

2. Using OREMORPHISMS, check that result.

3. Following the method explained in Exercise 20, prove that R is equivalent to the following block-diagonal matrix

$$\bar{R} = V R U^{-1} = \begin{pmatrix} \delta^2 - 1 & 0 & 0 \\ 0 & \delta^2 + 1 & -4\partial\delta \end{pmatrix},$$

where:

$$U = \begin{pmatrix} 1 & -1 & 0 \\ 1 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}, \quad V = \begin{pmatrix} 1 & -1 \\ 1 & 1 \end{pmatrix}.$$

4. Let $\mathcal{F} = C^\infty(\mathbb{R})$. Check that $\ker_{\mathcal{F}}((\delta^2 - 1)\cdot)$ is exactly formed by the $2h$ -periodic smooth functions.
5. Deduce that $\ker_{\mathcal{F}}(\bar{R}\cdot)$ is defined by

$$\forall \xi \in \mathcal{F}, \quad \begin{cases} z_1(t) = \psi(t), \\ z_2(t) = 4\dot{\xi}(t-h), \\ v(t) = \xi(t-2h) + \xi(t), \end{cases}$$

where ψ is an arbitrary $2h$ -periodic smooth function.

6. Deduce that the \mathcal{F} -solutions of (3) are defined by

$$\begin{pmatrix} y_1(t) \\ y_2(t) \\ u(t) \end{pmatrix} = U^{-1} \begin{pmatrix} z_1(t) \\ z_2(t) \\ v(t) \end{pmatrix} = \begin{pmatrix} \frac{1}{2}\psi(t) + 2\dot{\xi}(t-h) \\ -\frac{1}{2}\psi(t) + 2\dot{\xi}(t-h) \\ \xi(t-2h) + \xi(t) \end{pmatrix},$$

where ψ (resp., ξ) is an arbitrary $2h$ -periodic smooth (resp., smooth) function.

Exercise 26 We consider the model of a flexible rod with a torque

$$\begin{cases} \dot{y}_1(t) - \dot{y}_2(t-1) - u(t) = 0, \\ 2\dot{y}_1(t-1) - \dot{y}_2(t) - \dot{y}_2(t-2) = 0, \end{cases} \quad (13)$$

studied in H. Mounier, J. Rudolph, M. Petitot, M. Fliess, “A flexible rod as a linear delay system”, in *Proceedings of 3rd European Control Conference*, Rome (Italy), 1995.

Let $D = \mathbb{Q}[\partial; \text{id}, \frac{d}{dt}][\delta; \alpha, 0]$ be the commutative polynomial ring of OD time-delay operators with rational constant coefficients,

$$R = \begin{pmatrix} \partial & -\partial\delta & -1 \\ 2\partial\delta & -\partial\delta^2 - \partial & 0 \end{pmatrix} \in D^{2 \times 3}$$

the presentation matrix of (13) and $M = D^{1 \times 3}/(D^{1 \times 2}R)$ the D -module finitely presented by R .

1. Using ORE MORPHISMS, prove that M can be decomposed.

2. Using OREMORPHISMS, prove that R is equivalent to the following block-diagonal matrix

$$\bar{R} = \begin{pmatrix} \partial & 0 & 0 \\ 0 & 1 & 0 \end{pmatrix},$$

where:

$$U = \begin{pmatrix} -2\delta & 1 + \delta^2 & 0 \\ 1 & -\frac{\delta}{2} & 0 \\ \partial & -\partial\delta & -1 \end{pmatrix} \in \text{GL}_3(D), \quad V = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \in \text{GL}_2(D).$$

3. Integrating the trivial linear OD system $\bar{R}\bar{\eta} = 0$, prove that the general solution of the linear OD time-delay system $R\eta = 0$ is defined by

$$\begin{pmatrix} y_1(t) \\ y_2(t) \\ u(t) \end{pmatrix} = \begin{pmatrix} \frac{1}{2}c - z_3(t-2) - z_3(t) \\ c - 2z_3(t-1) \\ \dot{z}_3(t-2) - \dot{z}_3(t) \end{pmatrix},$$

where c is an arbitrary real constant and z_3 an arbitrary smooth function,

Exercise 27 We consider again Example 19.

- Using the command SYZGYMODULE, compute $\ker_D(\bar{P})$, $\text{im}_D(\bar{P}) = \ker_D((I_2 - \bar{P}))$, $\ker_D(\bar{Q})$ and $\text{im}_D(\bar{Q}) = \ker_D((1 - \bar{Q}))$.
- Check that depending on the \bar{P} 's, either $\ker_D(\bar{P})$ or $\text{im}_D(\bar{P})$ is not a free left D -module.

Hint. We recall that we can prove that the left $D = A_1(\mathbb{Q})$ -module $D^{1 \times 2}/(D(\partial - t))$ is not free.

- Conclude that R is not equivalent to a matrix of the form $\bar{R} = (\alpha \ 0)$, where $\alpha \in D$, over D .
- Consider the $E = B_1(\mathbb{Q}) = \mathbb{Q}(t) [\partial; \text{id}, \frac{d}{dt}]$ -module $N = E^{1 \times 2}/(ER) = E \otimes_D M$. Show that \bar{P} and \bar{Q} define an idempotent of the ring $\text{end}_E(N)$, i.e., N is a decomposable left E -module.
- Using the command SYZGYMODULERAT, compute $\ker_E(\bar{P})$, $\text{im}_E(\bar{P}) = \ker_E((I_2 - \bar{P}))$, $\ker_E(\bar{Q})$ and $\text{im}_E(\bar{Q}) = \ker_E((1 - \bar{Q}))$ and prove that they are free left E -modules.
- Conclude that R is equivalent to $\bar{R} = RU^{-1} = (\partial \ 0)$ over E , where:

$$U^{-1} = \begin{pmatrix} t & 1 \\ \partial & \frac{1}{t}\partial \end{pmatrix}.$$

Note the singularity of U^{-1} at $t = 0$.

- However, since M can be decomposed over D , following Exercise 14, prove that the general solution $\eta \in \mathcal{F}^2$ of $R\eta = 0$, where $\mathcal{F} = C^\infty(\mathbb{R}_+)$, is defined by:

$$\forall \xi_1, \xi_2 \in \mathcal{F}, \forall c \in \mathbb{R}, \quad \begin{cases} \eta_1(t) = ct + t^2 \xi_1(t) + t \dot{\xi}_2(t) - \xi_2(t), \\ \eta_2(t) = t \dot{\xi}_1(t) + 2 \xi_1(t) + \ddot{\xi}_2(t). \end{cases}$$

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