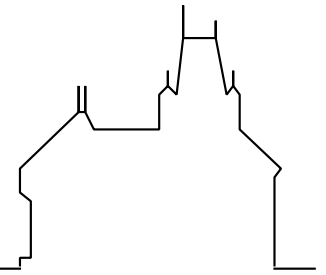


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Solving linear difference equations with coefficients in rings with idempotent representations*

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ABSTRACT

We introduce a general reduction strategy that enables one to search for solutions of parameterized linear difference equations in difference rings. Here we assume that the ring itself can be decomposed by a direct sum of integral domains (using idempotent elements) that enjoys certain technical features and that the coefficients of the difference equation are not degenerated. Using this mechanism we can reduce the problem to find solutions in a ring (with zero-divisors) to search solutions in several copies of integral domains. Utilizing existing solvers in this integral domain setting, we obtain a general solver where the components of the linear difference equations and the solutions can be taken from difference rings that are built e.g., by $R\Pi\Sigma$ -extensions over $\Pi\Sigma$ -fields. This class of difference rings contains, e.g., nested sums and products, products over roots of unity and nested sums defined over such objects.

KEYWORDS

linear difference equations, difference rings, idempotent elements

1 INTRODUCTION

In the following we denote by (\mathbb{E}, σ) a *difference ring (resp. field)*, this means that \mathbb{E} is a ring (resp. field) \mathbb{E} equipped with a ring (resp. field) automorphism $\sigma : \mathbb{E} \rightarrow \mathbb{E}$. We call (\mathbb{E}, σ) *computable* if the basic operations of \mathbb{E} and σ are computable. We define the *ring of constants* of (\mathbb{E}, σ) by $\mathbb{K} = \text{const}_\sigma \mathbb{E} = \{c \in \mathbb{E} \mid \sigma(c) = c\}$. By construction \mathbb{K} will be a field, called the *constant field* of (\mathbb{E}, σ) .

Given such a difference ring (\mathbb{E}, σ) with a constant field \mathbb{K} , we are interested in the following problem: Given $\mathbf{a} = (a_0, \dots, a_m) \in \mathbb{E}^{m+1}$ and $\mathbf{f} = (f_1, \dots, f_d) \in \mathbb{E}^d$, find (if this is possible) a finite representation of all solutions $g \in \mathbb{E}$ and $c_1, \dots, c_d \in \mathbb{K}$ of the *parameterized linear difference equation* (in short PLDE)

$$a_0 g + a_1 \sigma(g) + \dots + a_m \sigma^m(g) = c_1 f_1 + \dots + c_d f_d \quad (1)$$

with coefficients \mathbf{a} and parameters \mathbf{f} . The solution set is defined by

$$V = V(\mathbf{a}, \mathbf{f}, \mathbb{E}) = \{(c_1, \dots, c_d, g) \in \mathbb{K}^d \times \mathbb{E} \mid (1) \text{ holds}\}$$

which forms a \mathbb{K} -subspace of $\mathbb{K}^d \times \mathbb{E}$. We say that *we can compute all solutions in (\mathbb{E}, σ) of an explicitly given (1)* if V is a finite dimensional vector space and one can compute a basis of V . In particular, if \mathbb{E} is an integral domain and $a_0 a_m \neq 0$, we have $\dim(V) \leq m + n$ by [7, Thm. XII (page 272)]. In this case we say that *we can solve (in general) parameterized linear difference equations in (\mathbb{A}, σ)* if one can compute a basis of $V(\mathbf{a}, \mathbf{f}, \mathbb{E})$ for any $\mathbf{0} \neq \mathbf{a} \in \mathbb{E}^{m+1}$ and $\mathbf{f} \in \mathbb{E}^d$.

The problem to solve PLDEs (so far only in a field or integral domain \mathbb{E}) plays a central rule in symbolic summation and various

algorithms. It covers as special cases the telescoping problem ($\mathbf{a} = (1, -1)$, $\mathbf{f} \in \mathbb{E}^1$) for, e.g., hypergeometric products [9], the creative telescoping problem ($\mathbf{a} = (1, -1)$ with appropriately chosen $\mathbf{f} \in \mathbb{E}^d$) for, e.g., hypergeometric products [28], or recurrence solving ($d = 1$) for, e.g., rational or hypergeometric solutions [2, 16, 17]. The parameterized version is used also in holonomic summation [6] and generalizations of it [5]. Further details can found, e.g., in [26].

In particular, Karr's pioneering summation algorithm [12] established a highly general solver for first-order PLDEs in the setting of his $\Pi\Sigma$ -field extensions (Def. 19). In this way, the coefficients a_i , parameters f_i and the solutions g can be given in a $\Pi\Sigma$ -field (\mathbb{E}, σ) that is built formally by indefinite nested sums and products. Only recently, his general first-order solver has been pushed forward in [3] to the higher-order case (including also a solver to find all hypergeometric solutions over \mathbb{E}), that covers most of the summation algorithms mentioned above as special cases.

In this article we aim at further generalizations allowing in addition difference rings that are built by basic $R\Pi\Sigma$ -ring extensions [23, 24] (Def. 15) where also products over roots of unity like $(-1)^n$ can arise. Based on the observation that such rings can be decomposed by a direct sum of integral domains using idempotent elements (which is one of the key tools in the Galois theory of difference equations [10, 27]), we will develop in Section 2 a general strategy to solve non-degenerated PLDEs in idempotent difference rings (Def. 1). Inspired by [15, 18] we separate the potential solutions in their different components (Thm. 9) and try to combine them accordingly to the full solution (Thm. 14). Utilizing this machinery, we will invoke in Section 3 the general $\Pi\Sigma$ -field solver [3] (and variants of it) implemented within the summation package Sigma [21] to derive various new algorithms (see Theorems 25 and 31) in order to solve non-degenerated PLDEs in basic $R\Pi\Sigma$ -rings defined over $\Pi\Sigma$ -field-extensions. As a special case, the ground field can be, e.g., the mixed multibasic difference field [4] introduced in Remark 26. After a concrete example in Section 4 we conclude with Section 5.

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2 PLDES IN IDEMPOTENT DIFFERENCE RINGS

It will be convenient to denote by $s \bmod \lambda$ with $s \in \mathbb{Z}$ the unique value $l \in \{0, \dots, \lambda - 1\}$ with $\lambda \mid s - l$.

Definition 1. Let (\mathbb{E}, σ) be a difference ring and let $e_s \in \mathbb{E}$ with $0 \leq s < \lambda$ be elements such that

- they are idempotent (i.e., $e_s^2 = e_s$),
- pairwise orthogonal (i.e., $e_s e_t = 0$ if $s \neq t$),
- and $\sigma(e_s) = e_{s+1 \bmod \lambda}$.

If (\mathbb{E}, σ) can be decomposed in the form

$$\mathbb{E} = e_0 \mathbb{E} \oplus e_1 \mathbb{E} \oplus \dots \oplus e_{\lambda-1} \mathbb{E} \quad (2)$$

such that $e_i \mathbb{E}$ forms an computable integral domain, then (\mathbb{E}, σ) is called an *idempotent difference ring of order λ* .

Note that, if (\mathbb{E}, σ) is an idempotent difference ring of order λ then $(e_s \mathbb{E}, \sigma^\lambda)$ is a difference ring and σ is a difference ring isomorphism¹ between $(e_s \mathbb{E}, \sigma^\lambda)$ and $(e_{s+1 \bmod \lambda} \mathbb{E}, \sigma^\lambda)$.

Lemma 2. Let (\mathbb{E}, σ) be an idempotent difference ring of order λ and let $g = \sum_{s=0}^{\lambda-1} e_s g_s \in \mathbb{E}$, then applying σ means that the component $e_s g_s$ is moved cyclically to $(e_{s+1 \bmod \lambda} \mathbb{E}, \sigma^\lambda)$.

PROOF. Fix s with $0 \leq s < \lambda$, since $g_s \in \mathbb{E}$ we can write $g_s = \sum_{i=0}^{\lambda-1} e_i h_i$ for some $h_i \in \mathbb{E}$. Now applying σ to $e_s g_s$ gives:

$$\begin{aligned} \sigma(e_s g_s) &= \sigma \left(e_s \sum_{i=0}^{\lambda-1} e_i h_i \right) = \sigma(e_s) \sum_{i=0}^{\lambda-1} \sigma(e_i) \sigma(h_i) \\ &= e_{s+1 \bmod \lambda} \sum_{i=0}^{\lambda-1} e_{i+1 \bmod \lambda} \sigma(h_i) = e_{s+1 \bmod \lambda} \sigma(h_s). \end{aligned}$$

Since $\sigma(h_s) \in \mathbb{E}$ we have that $\sigma(e_s g_s) \in e_{s+1 \bmod \lambda} \mathbb{E}$. \square

For an idempotent difference ring (\mathbb{E}, σ) of order λ , with idempotent elements $e_s \in \mathbb{E}$ with $0 \leq s < \lambda$ the structure given by Lemma 2 can be illustrated as follows:

$$\mathbb{E} = e_0 \mathbb{E} \oplus e_1 \mathbb{E} \oplus \dots \oplus e_{\lambda-2} \mathbb{E} \oplus e_{\lambda-1} \mathbb{E}.$$

The following lemma is immediate.

Lemma 3. Let (\mathbb{E}, σ) be an idempotent difference ring of order λ and let $g = \sum_{s=0}^{\lambda-1} e_s g_s \in \mathbb{E}$ and $j \in \mathbb{N}$ then

$$\sigma^j(g) = \sum_{s=0}^{\lambda-1} e_{s+j \bmod \lambda} \sigma^j(g_s) = \sum_{s=0}^{\lambda-1} e_s \sigma^j(g_{s-j \bmod \lambda}). \quad (3)$$

Definition 4. Let (\mathbb{E}, σ) be an idempotent difference ring of order λ with idempotent elements $e_s \in \mathbb{E}$ with $0 \leq s < \lambda$. Then $\pi : \mathbb{E} \rightarrow \mathbb{E}$ with $\pi(g) \mapsto g_0$ where $g = \sum_{s=0}^{\lambda-1} e_s g_s$ is called a *projection*.

In this article we will always consider the projection on the first component, however each projection to an arbitrary component would do the job. The following lemma summarizes several properties of the projection.

¹A difference isomorphism $\tau : \mathbb{A}_1 \rightarrow \mathbb{A}_2$ between two difference rings (\mathbb{A}_i, σ_i) with $i = 1, 2$ is a ring isomorphism with $\tau(\sigma_1(f)) = \sigma_2(\tau(f))$ for all $f \in \mathbb{A}_1$.

Lemma 5. Let (\mathbb{E}, σ) be an idempotent difference ring of order λ with idempotent elements $e_s \in \mathbb{E}$ with $0 \leq s < \lambda$ and let $\pi : \mathbb{E} \rightarrow \mathbb{E}$ be a projection. For $g, h \in \mathbb{E}$ we have

$$\pi(g+h) = \pi(g) + \pi(h) \quad \text{and} \quad \pi(g \cdot h) = \pi(g) \cdot \pi(h). \quad (4)$$

In addition, for $j \in \mathbb{N}$ and $0 \leq s < \lambda$ we have

$$\pi(\sigma^j(e_s)) = \begin{cases} 1 & \text{if } s+j = 0 \pmod{\lambda} \\ 0 & \text{if } s+j \neq 0 \pmod{\lambda}, \end{cases} \quad (5)$$

and for $j \in \mathbb{N}$ and $g = \sum_{s=0}^{\lambda-1} e_s g_s$ we have

$$\pi(g) = e_0 g \quad \text{and} \quad \pi(\sigma^j(g)) = \sigma^j(g_{-j \bmod \lambda}) \quad (6)$$

PROOF. Let $g = \sum_{s=0}^{\lambda-1} e_s g_s \in \mathbb{E}$ and $h = \sum_{s=0}^{\lambda-1} e_s h_s \in \mathbb{E}$ then $g+h = \sum_{s=0}^{\lambda-1} e_s (g_s + h_s) \in \mathbb{E}$ and hence $\pi(g+h) = g_0 + h_0 = \pi(g) + \pi(h)$. Similarly, since $g \cdot h = \sum_{s=0}^{\lambda-1} e_s (g_s \cdot h_s) \in \mathbb{E}$ we have $\pi(g \cdot h) = g_0 \cdot h_0 = \pi(g) \cdot \pi(h)$. For $j \in \mathbb{N}$, $0 \leq s < \lambda$ we have that $\sigma^j(e_s) = e_{s+j \bmod \lambda}$, hence $\pi(\sigma^j(e_s)) = \pi(e_{s+j \bmod \lambda})$ which clearly evaluates to 1 if $s+j = 0 \pmod{\lambda}$ and to 0 if $s+j \neq 0 \pmod{\lambda}$. Finally, from Lemma 3 we know that $\sigma^j(g) = \sum_{s=0}^{\lambda-1} e_s \sigma^j(g_{s-j \bmod \lambda})$, hence $\pi(\sigma^j(g)) = \sum_{s=0}^{\lambda-1} \pi(e_s) \pi(\sigma^j(g_{s-j \bmod \lambda})) = \pi(\sigma^j(g_{-j \bmod \lambda}))$. Since $\pi(\sigma^j(g_{-j \bmod \lambda})) = e_0 \sigma^j(g_{-j \bmod \lambda}) = \sigma^j(e_{-j \bmod \lambda} g_{-j \bmod \lambda})$ we have that $\sigma^j(g) = \sigma^j(g_{-j \bmod \lambda})$. \square

Definition 6. Let (\mathbb{E}, σ) be an idempotent difference ring of order λ and let $\pi : \mathbb{E} \rightarrow \mathbb{E}$ be a projection. For $\mathbf{a} = (a_0, a_1, \dots, a_m) \in \mathbb{E}^{m+1}$ we define the $(m+1)\lambda - m \times (m+1)\lambda$ *shift projection matrix* by

$M_{\sigma, \pi}(\mathbf{a}) :=$

$$\begin{pmatrix} \pi(p_0) & \pi(p_1) & \dots & \pi(p_m) & 0 & 0 & \dots & 0 \\ 0 & \pi(\sigma(p_0)) & \dots & \pi(\sigma(p_{m-1})) & \pi(\sigma(p_m)) & 0 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & 0 & \pi(\sigma^k(p_0)) & \dots & \pi(\sigma^k(p_m)) \end{pmatrix},$$

where $k := (m+1)\lambda - m - 1$.

Definition 7. Let (\mathbb{E}, σ) be an idempotent difference ring of order λ and let $\pi : \mathbb{E} \rightarrow \mathbb{E}$ be a projection. A vector $\mathbf{a} = (a_0, a_1, \dots, a_m) \in \mathbb{E}^{m+1}$ is called *non-degenerate* if the shift projection matrix $M_{\sigma, \pi}(\mathbf{a})$ has full rank, i.e., the rows are linearly independent. Likewise, a linear difference operator $\sum_{i=0}^m a_i \sigma^i \in \mathbb{E}[\sigma]$ with $a_i \in \mathbb{E}$ is called *non-degenerate* if \mathbf{a} is *non-degenerate*.

Note, that for instance a linear difference operator $L = \sum_{i=0}^m a_i \sigma^i \in \mathbb{E}[\sigma]$ that is a multiple of an idempotent element e_i i.e., $e_i \mid a_i$ for all $0 \leq i \leq m$ is not non-degenerate, since for such an operator the shift projection matrix would contain a zero row. Similarly, L for which all coefficients vanish for a certain component is as well degenerate, since for such an operator the shift projection matrix would contain $m+1$ zero columns, see Example 12 below.

In the following lemma, we state an immediate criterion which implies that a linear difference operator is *non-degenerate*.

Lemma 8. Let (\mathbb{E}, σ) be an idempotent difference ring of order λ and let $\pi : \mathbb{E} \rightarrow \mathbb{E}$ be a projection. A linear difference operator $L := \sum_{i=0}^m p_i \sigma^i \in \mathbb{E}[\sigma]$, with $a_i \in \mathbb{E}$, is *non-degenerate* if either a_m or a_0 is a unit in \mathbb{E} .

Given a non-degenerate linear difference operator, the following theorem shows, that it is possible to define non-zero linear difference operators for each component. It is inspired by [15, 18].

Theorem 9. Let (\mathbb{E}, σ) be an idempotent difference ring of order λ with idempotent elements $e_s \in \mathbb{E}$ with $0 \leq s < \lambda$, let $\pi : \mathbb{E} \rightarrow \mathbb{E}$ be a projection and let $\mathbf{a} = (a_0, \dots, a_m) \in \mathbb{E}^{m+1}$ with $a_m \neq 0$ be non-degenerated. Consider the linear difference equation

$$\sum_{i=0}^m a_i \sigma^i(g) = \varphi. \quad (7)$$

with $\varphi \in \mathbb{E}$, which is satisfied by $g = \sum_{s=0}^{\lambda-1} e_s g_s \in \mathbb{E}$ and let $k \in \mathbb{N}$ with $0 \leq k < \lambda$. Then there exist $b_{k,i} \in e_k \mathbb{E}$, not all zero, and $\varphi_k \in e_k \mathbb{E}$ such that

$$\sum_{i=0}^m b_{k,i} (\sigma^\lambda)^i(g_k) = \varphi_k. \quad (8)$$

If (\mathbb{E}, σ) is computable, then the $b_{k,i}$ and φ_k can be computed.

PROOF. From (7) we can deduce for $j \in \mathbb{N}$ that

$$\sigma^j \left(\sum_{i=0}^m a_i \sigma^i(g) \right) = \sigma^j(\varphi) \quad (9)$$

or equivalently

$$\sum_{i=0}^m \sigma^j(a_i) \left(\sigma^{i+j}(e_0) \sigma^{i+j}(g_0) + \dots \right. \\ \left. \dots + \sigma^{i+j}(e_{\lambda-1}) \sigma^{i+j}(g_{\lambda-1}) \right) = \sigma^j(\varphi).$$

Applying the projection π and using Lemma 5 yields

$$\sum_{i=0}^m \pi(\sigma^j(a_i)) \pi(\sigma^{i+j}(g_{-(i+j) \bmod \lambda})) = \pi(\sigma^j(\varphi)),$$

since for $1 \leq l < \lambda$,

$$\pi(\sigma^{i+j}(e_l)) = \begin{cases} 1 & \text{if } l = -(i+j) \pmod{\lambda} \\ 0 & \text{if } l \neq -(i+j) \pmod{\lambda}. \end{cases}$$

Now, by Lemma 3 and Lemma 5 we find

$$\sum_{i=0}^m \pi(\sigma^j(a_i)) \sigma^{i+j}(g_{-(i+j) \bmod \lambda}) = \pi(\sigma^j(\varphi)). \quad (10)$$

Now, plugging in $j = 0, 1, 2, \dots, (m+1)\lambda - m - 1$ into (10) yields the linear system

$$M_{\sigma, \pi}(\mathbf{a}) \cdot \begin{pmatrix} \sigma^0(g_{0 \bmod \lambda}) \\ \sigma^1(g_{-1 \bmod \lambda}) \\ \sigma^2(g_{-2 \bmod \lambda}) \\ \vdots \\ \sigma^v(g_{-k \bmod \lambda}) \end{pmatrix} = \begin{pmatrix} \pi(\sigma^0(\varphi)) \\ \pi(\sigma^1(\varphi)) \\ \pi(\sigma^2(\varphi)) \\ \vdots \\ \pi(\sigma^v(\varphi)) \end{pmatrix}, \quad (11)$$

where $v := (m+1)\lambda - m - 1$. Since \mathbf{a} is non-degenerate and hence $M_{\sigma, \pi}(\mathbf{a})$ has full rank, we can solve this system in terms of m variables. Finally, we can plug this solution into (8). Since this leads to a linear system of at most $m+1$ equations in $m+2$ variables, which has a nontrivial solution, we can determine the coefficients $b_{k,i}$ and φ_k of (8). In particular, if \mathbb{E} is computable, the $b_{k,i}$ and φ_k can be computed. \square

Remark 10. Let (\mathbb{E}, σ) be a field extension of a difference ring (\mathbb{A}, σ') , i.e., \mathbb{A} is a subring of \mathbb{E} and $\sigma|_{\mathbb{A}} = \sigma'$, and suppose that the $\mathbf{a} \in \mathbb{A}^{m+1}$ and $\phi \in \mathbb{E}$. Then, since we plug solutions of the linear system (11) into (8), the right-hand sides in (8) have the form

$$\varphi_k = \sum_{l=0}^s f_l \pi(\sigma^l(\varphi))$$

with $f_0, \dots, f_s \in \mathbb{A}$ for some $s \in \mathbb{N}$.

Example 11. Consider the idempotent difference ring $(\mathbb{Q}(x)[y], \sigma)$ with $\sigma(x) = x+1$ and $\sigma(y) = -y$ and the idempotent elements $e_0 = \frac{1-y}{2}$ and $e_1 = \frac{1+y}{2}$. Let $\mathbf{a} = (x, x, 1, y)$, then the shift projection matrix $M_{\sigma, \pi}(\mathbf{a})$ yields

$$\begin{pmatrix} x & x & 1 & -1 & 0 & 0 & 0 & 0 \\ 0 & 1+x & 1+x & 1 & 1 & 0 & 0 & 0 \\ 0 & 0 & 2+x & 2+x & 1 & -1 & 0 & 0 \\ 0 & 0 & 0 & 3+x & 3+x & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 & 4+x & 4+x & 1 & -1 \end{pmatrix},$$

which has full rank. If $g = e_0 g_0 + e_1 g_1 \in \mathbb{E}$ is a solution of

$$xg + x\sigma(g) + \sigma^2(g) + y\sigma^3(g) = 0$$

then we find for g_0 and g_1 :

$$x(1+x)(5+2x)g_0 + (7+7x-3x^2-2x^3)\sigma^2(g_0) \\ + 4(1+x)(\sigma^2)^2(g_0) + (1+2x)(\sigma^2)^3(g_0) = 0, \\ x(1+x)g_1 + (3+x-x^2)\sigma^2(g_1) - 2(\sigma^2)^2(g_1) + (\sigma^2)^3(g_1) = 0.$$

Note that even in the degenerated case it might be possible to use the method stated in the proof of Theorem 9 to construct non-zero linear difference equations for some of the components.

Example 12. Again we consider the idempotent difference ring $(\mathbb{Q}(x)[y], \sigma)$ with $\sigma(x) = x+1$ and $\sigma(y) = -y$ and the idempotent elements $e_0 = \frac{1-y}{2}$ and $e_1 = \frac{1+y}{2}$. Let $\mathbf{a} = (y-1, x(y+1), y-1, x(y+1))$, then the shift projection matrix $M_{\sigma, \pi}(\mathbf{a})$ yields

$$\begin{pmatrix} -2 & 0 & -2 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 2(1+x) & 0 & 2(1+x) & 0 & 0 & 0 \\ 0 & 0 & -2 & 0 & -2 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 2(3+x) & 0 & 2(3+x) & 0 \\ 0 & 0 & 0 & 0 & -2 & 0 & -2 & 0 \end{pmatrix},$$

which clearly doesn't have full rank. Still if $g = e_0 g_0 + e_1 g_1 \in \mathbb{E}$ is a solution of

$$(y-1)g + x(y+1)\sigma(g) + (y-1)\sigma^2(g) + x(y+1)\sigma^3(g) = 0$$

then the first component g_0 satisfies $g_0 + \sigma^2(g_0) = 0$ but we do not find a non-trivial linear difference equation for g_1 .

With this notion the following corollary is immediate.

Corollary 13. Let (\mathbb{E}, σ) and $\mathbf{a} \in \mathbb{E}^{m+1}$ be as stated in Theorem 9. Consider the PLDE (1) with $f_i \in \mathbb{E}$ and $c_i \in \mathbb{K}$, which is satisfied by $g = \sum_{s=0}^{\lambda-1} e_s g_s \in \mathbb{E}$ and let $k \in \mathbb{N}$ with $0 \leq k < \lambda$. Then there exist $b_{k,i} \in e_k \mathbb{E}$, not all zero, and $f_{k,j} \in e_k \mathbb{E}$ such that

$$\sum_{i=0}^m b_{k,i} (\sigma^\lambda)^i(g_k) = c_1 f_{k,1} + \dots + c_d f_{k,d}. \quad (12)$$

In particular, if (\mathbb{E}, σ) is computable, the $a_{k,i}$ and $f_{k,j}$ are computable.

We are now ready to obtain a general strategy to solve PLDEs under the assumption that one can solve PLDEs in $(e_0 \mathbb{E}, \sigma^\lambda)$. Note that the task to compute for $f_0, \dots, f_d \in e_k \mathbb{E}$ a basis of

$$\{(c_1, \dots, c_d) \in \mathbb{K}^d \mid c_1 f_1 + \dots + c_d f_d = 0\} \quad (13)$$

is a special case by setting $g = 0$ in (1).

Theorem 14. *Let (\mathbb{E}, σ) be an idempotent difference ring with the idempotent elements $e_0, \dots, e_{\lambda-1}$ and constant field \mathbb{K} , and let $\mathbf{a} \in \mathbb{E}^{m+1}$ and $\mathbf{f} \in \mathbb{E}^d$. If $\text{const}_{\sigma^\lambda} \mathbb{E} = e_0 \mathbb{K}$ and \mathbf{a} is non-degenerated, $V(\mathbf{a}, \mathbf{f}, \mathbb{E})$ has a finite basis. If (\mathbb{E}, σ) is computable and PLDEs in $(e_0 \mathbb{E}, \sigma^\lambda)$ can be computed, a basis of $V(\mathbf{a}, \mathbf{f}, \mathbb{E})$ can be computed.*

PROOF. We look for a basis of $V = V(\mathbf{a}, \mathbf{f}, \mathbb{E})$ over \mathbb{K} for a non-degenerated $\mathbf{a} \in \mathbb{E}^{m+1}$ and $\mathbf{f} \in \mathbb{E}^d$. By Corollary 13 there exist $b_{k,i} \in e_k \mathbb{E}$, not all zero, and $f_{k,j} \in e_k \mathbb{E}$ with (12). Since $e_k \mathbb{E}$ for $0 \leq k < \lambda$ are integral domains, we can take a finite basis $\{(e_k c_{j,1}^{(k)}, \dots, e_k c_{j,d}^{(k)}, e_k \gamma_j^{(k)})\}_{1 \leq j \leq \delta_k} \subseteq (e_k \mathbb{K})^d \times (e_k \mathbb{E})$ with $c_{j,l}^{(k)} \in \mathbb{K}$ of $V_k = V((b_{k,0}, \dots, b_{k,m}), (f_{k,1}, \dots, f_{k,d}), e_k \mathbb{E})$ over $e_k \mathbb{K}$. If $\delta_k = 0$ for some $0 \leq k < \lambda$ it follows that $V = \{0\}$ and we get the empty basis. Otherwise, we can take a basis of

$$W = \{(c_1, \dots, c_d, e_0 g_0 + \dots + e_{\lambda-1} g_{\lambda-1}) \in \mathbb{K}^d \times \mathbb{E} \mid (e_k c_1, \dots, e_k c_d, e_k g_k) \in V_k \text{ for } 0 \leq k < \lambda\}.$$

as follows. We define $C_k = (c_{j,l})_{1 \leq j \leq \delta_k, 1 \leq l \leq d}$ for $0 \leq k < \lambda$ and take a \mathbb{K} -basis, say

$$\{(d_{l,0,1}, \dots, d_{l,0,\delta_1}, \dots, d_{l,\lambda-1,1}, \dots, d_{l,\lambda-1,\delta_{\lambda-1}})\}_{1 \leq l \leq r},$$

of the \mathbb{K} -vector space

$$\{(d_{0,1}, \dots, d_{0,\delta_1}, \dots, d_{\lambda-1,1}, \dots, d_{\lambda-1,\delta_{\lambda-1}}) \in \mathbb{K}^{\delta_0 + \dots + \delta_{\lambda-1}} \mid (d_{0,1}, \dots, d_{0,\delta_0}) C_0 = \dots = (d_{\lambda-1,1}, \dots, d_{\lambda-1,\delta_{\lambda-1}}) C_{\lambda-1}\}.$$

• If $r > 0$, we proceed as follows. We define for $1 \leq l \leq r$ the elements

$$g_l = g_l^{(0)} + \dots + g_l^{(\lambda-1)} \in \mathbb{E}$$

with $g_l^{(k)} = d_{l,k,1} e_k \gamma_1^{(k)} + \dots + d_{l,k,\delta_k} e_k \gamma_{\delta_k}^{(k)}$ where $0 \leq k < \lambda$, and define for $1 \leq l \leq r$ the constants

$$(c_{l,1}, \dots, c_{l,d}) = (d_{l,0,1}, \dots, d_{l,0,\delta_1}) C_1 \in \mathbb{K}^d.$$

Then $B = \{(c_{l,1}, \dots, c_{l,d}, g_l)\}_{1 \leq l \leq r}$ forms a bases of W . Now we plug in the found basis elements into (1) and obtain linear constraints. Fulfilling them by combining the basis elements accordingly will lead finally to a basis of the solution space V . For this final step, take $C = (c_{l,i})_{1 \leq l \leq r, 1 \leq i \leq d}$ with $c_{l,i} \in \mathbb{K}$ and $\mathbf{g} = (g_1, \dots, g_r) \in \mathbb{E}^r$, and define

$$\mathbf{f}' := C \mathbf{f}^t - (a_m \sigma^m(\mathbf{g}) + \dots + a_0 \mathbf{g}) \in \mathbb{E}^r;$$

here applying σ to a vector means to apply σ to each component. Note that nonzero elements in \mathbf{f}' reflect the disagreement of the so far found basis B to be also a basis of V . To complete the construction, we compute for the vector space

$$W' = \{(\kappa_1, \dots, \kappa_r) \in \mathbb{K}^r \mid (\kappa_1, \dots, \kappa_r) \mathbf{f}'\} \quad (14)$$

the basis $\{(\kappa_{i,1}, \dots, \kappa_{i,r})_{1 \leq i \leq s} \subseteq \mathbb{K}^s$; here one collects the components of \mathbf{f}' w.r.t. the e_k for $0 \leq k < \lambda$ (which is justified since

$e_0, \dots, e_{\lambda-1}$ are linearly independent), derives the bases in the integral domains $e_k \mathbb{E}$ for each $0 \leq k < \lambda$ and computes the intersection of the corresponding vector spaces to get a basis of W' . If $s = 0$, $V = \{0\}$ and we get the empty basis of V . Otherwise, take $D = (\kappa_{i,j})_{1 \leq i \leq s, 1 \leq j \leq r}$ and define the entries of the matrix $(c'_{i,j})_{1 \leq i \leq s, 1 \leq j \leq d} := DC$ and the entries of the vector $(g'_1, \dots, g'_s) := D(g_1, \dots, g_r) \in \mathbb{E}^s$. By construction $\{(c'_{i,1}, \dots, c'_{i,d}, g'_i)\}_{1 \leq i \leq s} \subseteq \mathbb{K}^d \times \mathbb{E}$ is a basis of V .

• If $r = 0$, it follows that $V \subseteq \{0\}^d \times \mathbb{E}$, i.e., we only have to search for homogeneous solutions of (1). Using the above construction we get a basis of the form $\{(0, g'_i)\}_{1 \leq i \leq s} \cup \{(1, 0)\}$ of $V(\mathbf{a}, (0), \mathbb{E})$. This gives the basis $\{(0, \dots, 0, g'_i)\}_{1 \leq i \leq s} \subseteq \{0\}^d \times \mathbb{E}$ of V .

We observe that the construction above can be carried out explicitly if the algorithmic assumptions hold: First, we can compute the bases of V_i ; more precisely, we move the problem with the isomorphism $\sigma^{\lambda-i}$ to the zero component, solve it there and move it back with σ^i . Further, we can solve the various linear algebra problems in \mathbb{K} . Finally, $e_k \mathbb{E}$ ($0 \leq k < \lambda$) are integral domains and we can compute a basis of (14) (by assumption a basis of (13) can be computed). \square

3 SOLVERS FOR $(R)\Pi\Sigma$ -EXTENSIONS

We will now apply Theorem 14 to a rather general class of difference rings built by basic $R\Pi\Sigma$ -ring extensions [23, 24] that are defined over $\Pi\Sigma$ -field extensions [12]. Before we can state Theorem 25 below, we will present more details on the underlying construction.

Definition 15. A difference ring (\mathbb{E}, σ) is called an $R\Pi\Sigma$ -ring extension of a difference ring (\mathbb{A}, σ) if $\mathbb{A} = \mathbb{A}_0 \leq \mathbb{A}_1 \leq \dots \leq \mathbb{A}_e = \mathbb{E}$ is a tower of ring extensions with $\text{const}_{\sigma^e} \mathbb{E} = \text{const}_{\sigma^e} \mathbb{A}$ where for all $1 \leq i \leq e$ one of the following holds:

- $\mathbb{A}_i = \mathbb{A}_{i-1}[t_i]$ is a ring extension subject to the relation $t_i^\nu = 1$ for some $\nu > 1$ where $\frac{\sigma(t_i)}{t_i} \in (\mathbb{A}_{i-1})^*$ is a primitive ν th root of unity (t_i is called an R -monomial, and ν is called the order of the R -monomial);
- $\mathbb{A}_i = \mathbb{A}_{i-1}[t_i, t_i^{-1}]$ is a Laurent polynomial ring extension with $\frac{\sigma(t_i)}{t_i} \in (\mathbb{A}_{i-1})^*$ (t_i is called a Π -monomial);
- $\mathbb{A}_i = \mathbb{A}_{i-1}[t_i]$ is a polynomial ring extension with $\sigma(t_i) - t_i \in \mathbb{A}_{i-1}$ (t_i is called an Σ -monomial).

Depending on the occurrences of the $R\Pi\Sigma$ -monomials such an extension is also called a R - Π - Σ - $R\Pi$ - $R\Sigma$ - $\Pi\Sigma$ -ring extension.

For convenience we use $\mathbb{A}\langle t \rangle$ for three different meanings: it is the ring $\mathbb{A}[t]$ subject to the relation $t^\nu = 1$ if t is an R -monomial of order ν , it is the polynomial ring $\mathbb{A}[t]$ if t is a Σ -monomial, or it is the Laurent polynomial ring $\mathbb{A}[t, t^{-1}]$ if t is a Π -monomial. We will restrict $R\Pi\Sigma$ -ring extensions further to basic $R\Pi\Sigma$ -ring extensions [24].

Definition 16. Let (\mathbb{E}, σ) be a $R\Pi\Sigma$ -ring extension of (\mathbb{A}, σ) with $\mathbb{E} = \mathbb{A}\langle t_1 \rangle \dots \langle t_e \rangle$. We define the product group by

$$[\mathbb{A}^*]_{\mathbb{A}}^{\mathbb{E}} := \{f t_1^{m_1} \dots t_e^{m_e} \mid f \in \mathbb{A}^* \text{ and } m_i \in \mathbb{Z} \text{ where } m_i = 0 \text{ if } t_i \text{ is an } R\Sigma\text{-monomial}\}.$$

Then (\mathbb{E}, σ) is called a basic $R\Pi\Sigma$ -ring extension of (\mathbb{A}, σ) if for all Π -monomials t_i we have $\frac{\sigma(t_i)}{t_i} \in [\mathbb{A}^*]_{\mathbb{A}}^{\mathbb{A}\langle t_1 \rangle \dots \langle t_{i-1} \rangle}$ and for all R -monomials t_i we have $\frac{\sigma(t_i)}{t_i} \in \text{const}_{\sigma} \mathbb{A}^*$.

In the following we seek for algorithms that solve PLDEs in a basic $\Pi\Sigma$ -ring extension (\mathbb{E}, σ) of a difference field (\mathbb{F}, σ) with constant field \mathbb{K} . By Lemma 2.22 and Proposition 2.23 in [24] it turns out that one can collect several R -monomials to one specific R -monomial. Thus we assume from now on that (\mathbb{E}, σ) has the form

$$\mathbb{E} = \mathbb{F}[y]\langle t_1 \rangle \dots \langle t_e \rangle \quad (15)$$

where y is an R -monomial of order λ with $\alpha := \frac{\sigma(y)}{y} \in \mathbb{K}^*$ and where the t_i with $1 \leq i \leq e$ are $\Pi\Sigma$ -monomials with $\sigma(t_i) = \alpha_i t_i + \beta_i$ (note that either $\alpha_i = 1$ or $\alpha_i \in [\mathbb{F}^*]_{\mathbb{F}}^{\mathbb{E}}$ with $\beta_i = 0$). Now take

$$\tilde{e}_s = \tilde{e}_s(y) := \prod_{\substack{j=0 \\ j \neq \lambda-1-s}}^{\lambda-1} (y - \alpha^j)$$

for $0 \leq s < \lambda$. Since α is a λ th primitive root of unity, we have that $\tilde{e}_s(\alpha^{\lambda-1-s}) \neq 0$. Thus we can define

$$e_s = e_s(y) := \frac{\tilde{e}_s(y)}{\tilde{e}_s(\alpha^{\lambda-1-s})} \quad (16)$$

for $0 \leq s < \lambda$ which fulfill precisely the properties enumerated in Definition 1. In particular, by [24, Thm. 4.3] (compare also [27, Corollary 1.16] and [10]) it follows that (\mathbb{E}, σ) is an idempotent difference ring of order λ . In particular, it is constant-stable provided that the ground field (\mathbb{F}, σ) is constant-stable.

Definition 17. A difference ring (resp. field) (\mathbb{A}, σ) is called *constant-stable* if $\text{const}_{\sigma^k} \mathbb{A} = \text{const}_{\sigma} \mathbb{A}$ for all $k \in \mathbb{N} \setminus \{0\}$.

Theorem 18 ([24, Thm. 4.3]). *Let (\mathbb{E}, σ) be a basic $\Pi\Sigma$ -ring extension of a difference field (\mathbb{F}, σ) with (15) where y is an R -monomial of order λ with $\alpha = \frac{\sigma(y)}{y}$. Let $e_0, \dots, e_{\lambda-1}$ be the idempotent, pairwise orthogonal elements defined in (16) (that sum up to one). Then:*

- (1) *We get the direct sum (2) of the rings $e_s \mathbb{E}$ with the multiplicative identities e_s .*
- (2) *We have that $e_s \mathbb{E} = e_s \tilde{\mathbb{E}}$ with the integral domain*

$$\tilde{\mathbb{E}} := \mathbb{F}\langle t_1 \rangle \dots \langle t_e \rangle. \quad (17)$$

- (3) *For $0 \leq s < \lambda$, $(e_s \tilde{\mathbb{E}}, \sigma^\lambda)$ is a basic $\Pi\Sigma$ -ring extension of $(e_s \mathbb{F}, \sigma^\lambda)$.*
- (4) *σ is a difference ring isomorphism between $(e_s \tilde{\mathbb{E}}, \sigma^\lambda)$ and $(e_{s+1 \bmod \lambda} \tilde{\mathbb{E}}, \sigma^\lambda)$.*
- (5) *Further, if (\mathbb{F}, σ) is constant-stable, $\text{const}_{\sigma^\lambda} e_s \mathbb{E} = e_s \text{const}_{\sigma} \mathbb{F}$.*

In this particular setting, the used constructions in Section 2 and in Theorem 18 can be made more precise as follows. For $f \in \mathbb{E}$, the projection of the first component can be computed by

$$\pi(f) := \sum_{i=0}^{\lambda-1} e_i(y) f \Big|_{y \rightarrow \alpha^{\lambda-1-i}}.$$

Furthermore, define for $n \in \mathbb{N}$ and $f \in \mathbb{F}$ the σ -factorial

$$f^{\sigma, n} = \prod_{i=0}^{n-1} \sigma^i(f).$$

Then with $\sigma(t_i) = \alpha t_i + \beta_i$ (recall that $\alpha_i = 1$ or $\beta_i = 0$) we get $\sigma^\lambda(t_i) = \tilde{\alpha}_i t_i + \tilde{\beta}_i$ with $\tilde{\alpha}_i = \alpha^{\sigma, i}$ and $\tilde{\beta}_i = \sum_{l=0}^{i-1} \sigma^l(\beta)$. In particular, we can define for $0 \leq s < \lambda$ the ring automorphism $\sigma_s : \tilde{\mathbb{E}} \rightarrow \tilde{\mathbb{E}}$ with $\sigma_s(f) = \sigma^\lambda(f)$ for $f \in \mathbb{F}$ and

$$\sigma_s(t_i) = \tilde{\alpha}_i t_i + (\tilde{\beta}_i)_{y \rightarrow \alpha^{\lambda-1-s}} \quad (18)$$

for all $1 \leq i \leq e$. Then $(\tilde{\mathbb{E}}, \sigma_s)$ and $(e_s \tilde{\mathbb{E}}, \sigma^\lambda)$ are isomorphic with the difference ring isomorphism $\tau : \tilde{\mathbb{E}} \rightarrow e_s \tilde{\mathbb{E}}$ with $\tau(f) = e_s f$ for $f \in \tilde{\mathbb{E}}$; for further details we refer to [24, page 639]. In the following we prefer to work with $(\tilde{\mathbb{E}}, \sigma_s)$ instead of $(e_s \tilde{\mathbb{E}}, \sigma^\lambda)$. Note that this representation is also more convenient for implementations.

As observed in Theorem 18 we obtain the $\Pi\Sigma$ -ring extension $(\tilde{\mathbb{E}}, \sigma_s)$ of $(\mathbb{F}, \sigma^\lambda)$ where $\tilde{\mathbb{E}}$ is an integral domain. Thus we can take the quotient field $Q(\tilde{\mathbb{E}}) = \mathbb{F}\langle t_1 \rangle \dots \langle t_e \rangle$ and by naturally extending $\sigma_s : \tilde{\mathbb{E}} \rightarrow \tilde{\mathbb{E}}$ to $\sigma'_s : Q(\tilde{\mathbb{E}}) \rightarrow Q(\tilde{\mathbb{E}})$ with $\sigma'_s(\frac{a}{b}) = \frac{\sigma_s(a)}{\sigma_s(b)}$ we get a difference field $(Q(\tilde{\mathbb{E}}), \sigma'_s)$; from now on we do not distinguish anymore between σ'_s and σ_s .

Finally, we take the ring of fractions $Q(\mathbb{E}) = \{\frac{a}{b} \mid a \in \mathbb{E}, b \in \mathbb{E}^*\}$ which can be written in terms of the idempotent representation

$$Q(\mathbb{E}) = e_0 Q(\tilde{\mathbb{E}}) \oplus \dots \oplus e_{\lambda-1} Q(\tilde{\mathbb{E}}). \quad (19)$$

In particular, we can extend the automorphism $\sigma : \mathbb{E} \rightarrow \mathbb{E}$ to $\sigma : Q(\mathbb{E}) \rightarrow Q(\mathbb{E})$ by mapping $f = e_0 f_0 + \dots + e_{\lambda-1} f_{\lambda-1}$ with $f_i \in \tilde{\mathbb{E}}$ to $\sigma(f) = e_0 \sigma(f_{\lambda-1}) + e_1 \sigma(f_0) + \dots + e_{\lambda-1} f_{\lambda-2}$; compare [11, Sec. 1.3] and [10, Cor. 6.9].

Summarizing, also $(Q(\mathbb{E}), \sigma)$ is an idempotent difference ring of order λ as introduced in Definition 1 and it seems naturally to apply Theorem 14 to this more general situation. Here we note (compare also [24, Prop. 66]) that each component $(\tilde{\mathbb{E}}, \sigma_s)$ for $0 \leq s < \lambda$ is actually a special case of a $\Pi\Sigma$ -field-extension [12, 13].

Definition 19. A difference field (\mathbb{H}, σ) is called a $\Pi\Sigma$ -field extension of a difference field (\mathbb{H}_0, σ) if $\mathbb{H} = \mathbb{H}_0 \leq \mathbb{H}_1 \leq \dots \leq \mathbb{H}_e = \mathbb{F}$ is a tower of field extensions with $\text{const}_{\sigma^k} \mathbb{F} = \text{const}_{\sigma} \mathbb{H}$ where for all $1 \leq i \leq e$ one of the following holds:

- $\mathbb{H}_i = \mathbb{H}_{i-1}(t_i)$ is a rational function field extension with $\frac{\sigma(t_i)}{t_i} \in (\mathbb{H}_{i-1})^*$ (t_i is called a Π -field monomial);
- $\mathbb{H}_i = \mathbb{H}_{i-1}(t_i)$ is a rational function extension with $\sigma(t_i) - t_i \in \mathbb{H}_{i-1}$ (t_i is called a Σ -field monomial).

Here we will rely on the following property of $\Pi\Sigma$ -field extensions; the first statement has been shown in [12] for $\Pi\Sigma$ -fields. The second statement appears also in [25].

Proposition 20. *Let (\mathbb{E}, σ) be a $\Pi\Sigma$ -field/ $\Pi\Sigma$ -ring extension of a difference field (\mathbb{F}, σ) with $\mathbb{K} = \text{const}_{\sigma} \mathbb{F}$. Then:*

- (1) *For $k > 1$, (\mathbb{E}, σ^k) is a $\Pi\Sigma$ -field/ $\Pi\Sigma$ -ring extension of (\mathbb{F}, σ^k) .*
- (2) *If (\mathbb{F}, σ) is constant-stable, (\mathbb{E}, σ) is constant-stable.*

PROOF. (1) Let $k > 1$ and suppose that there is an $a \in \mathbb{E} \setminus \mathbb{F}$ with $\sigma^k(a) = a$. Define $h = a \sigma(a) \dots \sigma^{k-1}(a)$. By [25, Lemma 31.(3)] it follows that $h \notin \mathbb{F}$. Since $\frac{\sigma(h)}{h} = \frac{\sigma^k(a)}{a} = 1$, it follows that $h \in \text{const}_{\sigma} \mathbb{E} = \text{const}_{\sigma} \mathbb{F} \subseteq \mathbb{F}$, a contradiction. Note that for any Σ -monomial t with $\sigma(t) = t + \beta$ we have $\sigma^k(t) - t = \sum_{i=0}^{k-1} \sigma^i(\beta)$ and for any Π -monomial t with $\sigma(t) = \alpha t$ we have $\sigma^k(t)/t = \alpha^{\sigma, k}$. Thus the automorphism σ^k satisfies the requirements and consequently (\mathbb{E}, σ^k) is a $\Pi\Sigma$ -field/ $\Pi\Sigma$ -ring extension of (\mathbb{F}, σ^k) .

(2) Suppose that (\mathbb{F}, σ) is constant-stable and let $k > 1$. Then $\text{const}_{\sigma^k} \mathbb{F} = \text{const}_{\sigma} \mathbb{F}$. By statement (1), $\text{const}_{\sigma} \mathbb{F} = \text{const}_{\sigma} \mathbb{E}$ and thus $\text{const}_{\sigma^k} \mathbb{E} = \text{const}_{\sigma^k} \mathbb{E}$. Hence (\mathbb{E}, σ) is constant-stable. \square

In this particular scenario, we can refine Theorem 14 as follows.

Proposition 21. *Let (\mathbb{F}, σ) be a constant-stable difference field with constant field \mathbb{K} , and let (\mathbb{E}, σ) with (15) be a basic $R\Pi\Sigma$ -ring extension with only one R -monomial y with $\frac{\sigma(y)}{y} \in \mathbb{K}$ of order λ . Then one can solve non-degenerated PLDEs in (\mathbb{E}, σ) (resp. in $(Q(\mathbb{E}), \sigma)$) if (\mathbb{E}, σ) is computable and one can solve PLDEs in the $\Pi\Sigma$ -ring extension $(\tilde{\mathbb{E}}, \sigma_0)$ (resp. $\Pi\Sigma$ -field extension $(Q(\tilde{\mathbb{E}}), \sigma_0)$) of $(\mathbb{F}, \sigma^\lambda)$ with (17).*

PROOF. $(\tilde{\mathbb{E}}, \sigma_0)$ is a basic $\Pi\Sigma$ -ring extension of $(\mathbb{F}, \sigma^\lambda)$ by Theorem 18.(3), and thus taking the quotient field $Q(\tilde{\mathbb{E}})$, $(Q(\tilde{\mathbb{E}}), \sigma_0)$ is a $\Pi\Sigma$ -field extension of $(\mathbb{F}, \sigma^\lambda)$ by iterative application of [24, Cor. 2.6]. Since (\mathbb{F}, σ) is constant-stable, we get $\text{const}_{\sigma_0} Q(\tilde{\mathbb{E}}) = \text{const}_{\sigma_0} \tilde{\mathbb{E}} = \text{const}_{\sigma^\lambda} \mathbb{F} = \text{const}_{\sigma} \mathbb{F} = \mathbb{K}$. Finally, since we can solve PLDEs in $(\tilde{\mathbb{E}}, \sigma_0)$ (resp. in $(Q(\tilde{\mathbb{E}}), \sigma_0)$) by assumption, we can apply Theorem 14 and can compute all solutions of non-degenerated PLDEs in (\mathbb{E}, σ) (resp. in $(Q(\mathbb{E}), \sigma)$). \square

3.1 The general case: basic $R\Pi\Sigma$ -ring extensions over $\Pi\Sigma$ -field extensions

To activate Proposition 21 we have to take an appropriate difference field (\mathbb{F}, σ) such that (1) it is constant-stable and such that (2) PLDEs can be solved in $(\tilde{\mathbb{E}}, \sigma_0)$. As it turns out, both properties can be fulfilled if (\mathbb{F}, σ) itself is a $\Pi\Sigma$ -field extension of a difference field (\mathbb{G}, σ) that enjoys certain algorithmic properties. In this situation, the first property can be settled using Proposition 20 from above. To deal with the second property, we will introduce the following problems; a certain subset of them have been introduced originally in [14] (by analyzing Karr's (telescoping) algorithms in [12]).

Definition 22 ([3]). A difference field (\mathbb{F}, σ) with constant field \mathbb{K} is σ -computable if (\mathbb{E}, σ) is computable and the following holds.

- (1) One can factor multivariate polynomials over \mathbb{F} .
- (2) (\mathbb{F}, σ^s) is torsion free for any $s \in \mathbb{Z}^*$, i.e.,

$$\forall s, r \in \mathbb{Z}^* \forall f, g \in \mathbb{F}^* : f = \frac{\sigma^s(g)}{g} \wedge f^r = 1 \Rightarrow f = 1.$$
- (3) The Π -Regularity problem is solvable: Given (\mathbb{F}, σ) and $f, g \in \mathbb{F}^*$; find, if possible, an $n \geq 0$ with $f^{\sigma^n} = g$.
- (4) The Σ -Regularity problem is solvable: Given (\mathbb{F}, σ) , $r \in \mathbb{Z}^*$, $f, g \in \mathbb{F}^*$; find, if possible, $n \geq 0$ with $f^{\sigma^{r,0}} + \dots + f^{\sigma^{r,n}} = g$.
- (5) The parameterized pseudo-orbit problem is solvable: Given $f = (f_1, \dots, f_n) \in (\mathbb{F}^*)^d$; compute a \mathbb{Z} -basis of the module $M(f, \mathbb{F}) = \{(z_1, \dots, z_d) \in \mathbb{Z}^n \mid \exists g \in \mathbb{F}^* \frac{\sigma(g)}{g} = f_1^{z_1} \dots f_d^{z_d}\}$.
- (6) There is an algorithm that can compute all the hypergeometric candidates for equations with coefficients in (\mathbb{F}, σ) : Given a nonzero operator $L \in \mathbb{F}[\sigma]$; compute a finite set $S \subset \mathbb{F}$ such that for any $r \in \mathbb{F}^*$, if $\sigma - r$ is a right factor of L in $\mathbb{F}[\sigma]$, then $r = u \frac{\sigma(v)}{v}$ for some $u \in S$ and $v \in \mathbb{F}^*$.
- (7) PLDEs are solvable in (\mathbb{F}, σ) : Given $\mathbf{0} \neq \mathbf{a} \in \mathbb{F}^{m+1}$, $f \in \mathbb{F}^d$; compute a \mathbb{K} -basis of $V(\mathbf{a}, f, \mathbb{F})$.

Then using the brandnew framework summarized in [3, Thm. 10], we obtain the following result which has been implemented within the summation package Sigma.

Theorem 23 ([3]). *Let (\mathbb{E}, σ) be a (nested) $\Pi\Sigma$ -field extension of (\mathbb{F}, σ) . If (\mathbb{F}, σ) is σ -computable, then also (\mathbb{E}, σ) is σ -computable.*

In particular, using [3, 14] (based on [12]) the properties given in Definition 22 simplify in the special case $\sigma = \text{id}$ as follows.

Theorem 24. *Let \mathbb{K} be a computable field where*

- (1) *polynomials can be factored in $\mathbb{K}[t_1, \dots, t_e]$,*
- (2) *a basis of $\{(z_1, \dots, z_d) \in \mathbb{Z}^d \mid 1 = \prod_{i=1}^d c_i^{z_i}\}$ can be computed,*
- (3) *one can recognize if $c \in k$ is an integer,*

then (\mathbb{K}, σ) with $\text{const}_{\sigma} K = \mathbb{K}$ is σ -computable.

We can now state our first algorithmic framework to solve non-degenerated PLDEs in $(R)\Pi\Sigma$ -extensions.

Theorem 25. *Let (\mathbb{F}, σ) be a $\Pi\Sigma$ -field extension of a difference field (\mathbb{G}, σ) and let (\mathbb{E}, σ) be a basic $R\Pi\Sigma$ -ring extension of (\mathbb{F}, σ) with one R -monomial y with $\frac{\sigma(y)}{y} \in \text{const}_{\sigma} \mathbb{F}$ of order λ . Then one can solve non-degenerated PLDEs in the quotient ring $(Q(\mathbb{E}), \sigma)$ or in (\mathbb{E}, σ) if one of the following holds:*

- (1) *(\mathbb{G}, σ) is constant-stable and $(\mathbb{G}, \sigma^\lambda)$ is σ -computable.*
- (2) *$\text{const}_{\sigma} \mathbb{G} = \mathbb{G}$ satisfies the properties in Theorem 24.*
- (3) *$\text{const}_{\sigma} \mathbb{G} = \mathbb{G}$ is a rat. function field over an alg. number field.*

PROOF. (1) Since (\mathbb{G}, σ) is constant-stable, it follows that (\mathbb{F}, σ) is constant-stable by Proposition 20.(2). Furthermore, $(\mathbb{F}, \sigma^\lambda)$ is a $\Pi\Sigma$ -field extension of $(\mathbb{G}, \sigma^\lambda)$ by Proposition 20.(1) and thus $(Q(\tilde{\mathbb{E}}), \sigma_0)$ is a $\Pi\Sigma$ -field extension of $(\mathbb{G}, \sigma^\lambda)$. Since $(\mathbb{G}, \sigma^\lambda)$ is σ -computable, we conclude with Theorem 23 that also $(Q(\tilde{\mathbb{E}}), \sigma_0)$ is σ -computable, in particular property (7) in Definition 22 holds. Hence we can apply Proposition 21 and can solve all non-degenerated PLDEs in $(Q(\mathbb{E}), \sigma)$. Given a basis in $Q(\mathbb{E})$ one can filter out a basis of the subspace in \mathbb{E} by linear algebra².

(2) Since $\mathbb{G} = \text{const}_{\sigma} \mathbb{G}$, $\sigma|_{\mathbb{G}} = \text{id}$. Thus (\mathbb{G}, σ) is trivially constant-stable. In addition, if the properties of Theorem 24 are fulfilled, (\mathbb{G}, σ) is σ -computable and thus we can apply part (1).

(3) By [8] and [19, Thm. 3.5] it follows that the algorithms required in Theorem 24 are available. Thus we can apply part (2). \square

Remark 26. Theorem 25 (Case 3) covers, e.g., the rational ($v = 0$) or the mixed multibasic difference field (\mathbb{G}, σ) with $\mathbb{G} = \mathbb{K}(x, x_1, \dots, x_v)$ where $\mathbb{K} = K(q_1, \dots, q_v)$ is a rational function field (K itself is a rational function field over an algebraic number field) and with $\sigma|_{\mathbb{K}} = \text{id}$, $\sigma(x) = x + 1$ and $\sigma(x_i) = q_i x_i$ for $1 \leq i \leq v$.

3.2 Simplified algorithms for special ring cases

The PLDE solver summarized in Theorem 25 assumes that (\mathbb{G}, σ) is σ -computable. In the following we restrict ourselves to some interesting sub-classes of $R\Pi\Sigma$ -ring extensions where the Σ - and Π -regularity problem in Definition 22 (but also the hidden shift-equivalence problem within the tower of extensions) can be avoided. As a consequence one ends up at lighter implementations where most of the highly recursive algorithms from [12] can be skipped.

Let $(\mathbb{A}\langle t \rangle, \sigma)$ be a $\Pi\Sigma$ -ring extension of (\mathbb{A}, σ) with constant field $\mathbb{K} = \text{const}_{\sigma} \mathbb{A}$. Assume in addition that \mathbb{A} is an integral domain and that one can solve PLDEs in (\mathbb{A}, σ) . Then we can apply the following tactic [20] (which is inspired by [12] and is also the backbone strategy in [3]) to find a basis of $V = V(\mathbf{a}, f, \mathbb{A}\langle t \rangle)$ with $\mathbf{0} \neq \mathbf{a} = (a_0, \dots, a_m) \in \mathbb{A}\langle t \rangle^{m+1}$ and $f = (f_1, \dots, f_d) \in \mathbb{A}\langle t \rangle^d$. First, we bound the degree of the possible solutions: namely, we compute $a, b \in \mathbb{Z}$ such that for any $(c_1, \dots, c_d, \sum_{k=a}^{b'} g_i t^i) \in V$ we have $a \leq a'$ and $b' \leq b$; if t is a Σ -monomial we set $a = 0$

²In Section 3.2 we will provide improved algorithms to accomplish this task directly.

and search for b only. Then given such bounds a, b , we make the ansatz (1) with unknown $c_0, \dots, c_d \in \mathbb{K}$ and $g = \sum_{k=a'}^{b'} g_i t^i$ with unknown $g_a, \dots, g_b \in \mathbb{A}$. By comparing coefficients in (1) w.r.t. to the highest arising term we obtain a PLDE in (\mathbb{A}, σ) which has c_1, \dots, c_d and $g_b \in \mathbb{A}$ as solution. Solving this PLDE yields all possible candidates for g_b . Thus plugging these choices into (1) we can proceed recursively (by degree reduction) to nail down g_b and the remaining coefficients g_a, \dots, g_{b-1} .

Due to [3, Theorem 7] it follows that one can determine $b \in \mathbb{N}$ and $a = 0$ for a Σ -monomial t if one can solve PLDEs in (\mathbb{A}, σ) . Thus activating this machinery recursively yields the following result.

Proposition 27. *If one can solve PLDEs in (\mathbb{A}, σ) , then one can solve PLDEs in a Σ -extension $(\mathbb{A}\langle t_1 \dots t_e \rangle, \sigma)$ of (\mathbb{A}, σ)*

For Π -monomials one can utilize [3, Theorem 6] to compute the above bounds $a, b \in \mathbb{Z}$. If one applies this machinery recursively (as for Σ -monomials) one ends up at the requirement that the ground ring is σ -computable. In a nutshell, we rediscover the ring version of Theorem 25 – but this time we solve it directly without computing first all solutions in its quotient field.

In the following we adapt slightly the proof steps of [3, Theorem 6] yielding the more flexible Lemma 29. For its proof, we need in addition the following result.

Lemma 28. *Let $(\mathbb{F}\langle t_1 \dots t_e \rangle, \sigma)$ be a Π -ring extension of (\mathbb{F}, σ) with $\alpha_i = \frac{\sigma(t_i)}{t_i} \in \mathbb{F}^*$. Let $V = M(\alpha_1, \dots, \alpha_e, u)$ for some $u \in \mathbb{F}^*$. Then $V = \emptyset$ or $V = \mathbb{Z}(\lambda_1, \dots, \lambda_{e+1})$ for some $\lambda_i \in \mathbb{Z}$ with $\lambda_{e+1} > 0$.*

PROOF. Suppose that $V \neq \emptyset$. Suppose further that we can take $0 \neq (\lambda_1, \dots, \lambda_e, 0) \in V$. Then we get $g \in \mathbb{F}^*$ with $\frac{\sigma(g)}{g} = \alpha_1^{\lambda_1} \dots \alpha_e^{\lambda_e}$, not all λ_i being zero, which is not possible by [22, Thm. 9.1]. Consequently, for any nonzero vector in V we conclude that the last entry must be nonzero. Now take $\lambda = (\lambda_1, \dots, \lambda_{e+1}), \mu = (\mu_1, \dots, \mu_{e+1}) \in V \setminus \{0\}$. Then $\lambda_{e+1}, \mu_{e+1} \neq 0$. In particular, $\mathbf{a} = \mu_{e+1}\lambda - \lambda_{e+1}\mu \in V$. Since the last entry of \mathbf{a} is zero, it follows that $\mathbf{a} = \mathbf{0}$. Hence two nonzero vectors are linearly dependent and it follows that $V = \{(\lambda_1, \dots, \lambda_{e+1})\}\mathbb{Z}$ with $\lambda_{e+1} \neq 0$. If $\lambda_{e+1} < 0$, we can choose the alternative generator $(-\lambda_1, \dots, -\lambda_{e+1})$ with $-\lambda_{e+1} > 0$. \square

Lemma 29. *Let (\mathbb{E}, σ) with $\mathbb{E} = \mathbb{F}\langle t_1 \dots t_e \rangle$ be a Π -ring extension of (\mathbb{F}, σ) with $\alpha_i = \frac{\sigma(t_i)}{t_i} \in \mathbb{F}^*$. If one can solve the parameterized pseudo problem in (\mathbb{F}, σ) and can find all hypergeometric candidates in (\mathbb{F}, σ) , one can bound the degrees of the solutions w.r.t. t_e .*

PROOF. Let $\mathbf{f} = (f_1, \dots, f_d) \in \mathbb{E}^d$ and $(a_0, \dots, a_m) \in \mathbb{E}^{m+1}$ with $a_0 a_m \in \mathbb{E}^*$ and suppose that $g \in \mathbb{E}$ is a solution of (1). Let l_e be the highest degree in g w.r.t. t_e . In the following we take the lexicographic order $<$ on $M = \{t_1^{m_1} \dots t_e^{m_e} \mid n_1, \dots, n_e \in \mathbb{Z}\}$ with $t_1 < t_2 < \dots < t_e$, and $t_i^a < t_i^b$ iff $a < b$. Let $\tilde{g} = h t_1^{\lambda_1} \dots t_e^{\lambda_e}$ be the highest term in g ; note that $\lambda_e = l_e$. Further, let $\mu = t_1^{\mu_1} \dots t_e^{\mu_e} \in M$ be the largest monomial of the coefficients in \mathbf{a} , and let $\tilde{a}_i \in \mathbb{F}$ for $0 \leq i \leq m$ be the corresponding coefficient of μ ; note that one of the \tilde{a}_i is nonzero. Take $L := \tilde{a}_0 + \tilde{a}_1 \sigma + \dots + \tilde{a}_m \sigma^m \in \mathbb{F}[\sigma]$.

Now suppose that $L(\tilde{g}) = 0$ and define $\alpha = \frac{\sigma(h)}{h} \alpha_1^{\lambda_1} \dots \alpha_e^{\lambda_e} \in \mathbb{F}^*$. Note that for $\tilde{L} = \sigma - \alpha \in \mathbb{F}[\sigma]$ we have $\tilde{L}(\tilde{g}) = 0$ by construction. Now we follow the arguments of [3, Lemma 2]. Let $L = Q\tilde{L} + R$ be the right-division of L by \tilde{L} with $Q \in \mathbb{F}[\sigma]$ and $R \in \mathbb{F}$. Since $0 =$

$L(\tilde{g}) = Q\tilde{L}(\tilde{g}) + R = R$, \tilde{L} is a right-factor of L . By assumption we can compute a set S which contains all hypergeometric candidates of \tilde{L} . Thus we can take $u \in S$ with $\frac{\sigma(h)}{h} \alpha_1^{\lambda_1} \dots \alpha_e^{\lambda_e} = \alpha = u \frac{\sigma(w)}{w}$. Consequently, we get $\alpha_1^{\lambda_1} \dots \alpha_e^{\lambda_e} u^{-1} = \frac{\sigma(w')}{w'}$ for some $w' \in \mathbb{F}^*$. Now compute a basis B_u of $V_u = M(\alpha_1, \dots, \alpha_e, u^{-1}; \mathbb{F})$. By Lemma 28 we can assume that $B_u = \{(v_{u,1}, \dots, v_{u,e+1})\} \in \mathbb{Z}^{e+1}$ with $v_{u,e+1} > 0$. Note that it follows even that $v_{u,e+1} = 1$ and $l_e = \lambda_e = v_{u,e}$. Thus to bound the leading coefficient w.r.t. t_e we proceed as follows: We loop through all $u \in S$ and compute a basis B_u of V_u and take

$$C = \max\{v_{u,e} \mid V_u = (v_{u,1}, \dots, v_{u,e}, 1)\mathbb{Z} \text{ for } u \in S\}.$$

Summarizing, let l_e be the highest degree in the solution g w.r.t. t_e and let $\tilde{g} = h t_1^{\lambda_1} \dots t_e^{\lambda_e}$ be the highest term in g . If $\tilde{L}(\tilde{g}) = 0$, then $l_e \in C$, i.e., $C \neq \emptyset$ and $l_e \leq \max(C)$. Otherwise, if $C = \emptyset$ or $\tilde{L}(\tilde{g}) \neq 0$, we conclude as follows. We note that $\tilde{L}(\tilde{g}) = h' t_1^{\lambda_1} \dots t_e^{\lambda_e}$ for some $h' \in \mathbb{F}^*$. Since \tilde{g} is the largest term in our solution y and since \tilde{L} is the contribution of the highest term in (1), it follows by coefficient comparison in (1) that $\tilde{L}(\tilde{g}) t_1^{m_1} \dots t_e^{m_e} = h' t_1^{m_1 + \lambda_1} \dots t_e^{m_e + \lambda_e}$ for some $h' \in \mathbb{F}^*$ must arise in $c_1 f_1 + \dots + c_d f_d$. Thus, if d_i is the largest exponent in f_i w.r.t. t_e , we get $m_e + \lambda_e < \max(d_1, \dots, d_e)$. In conclusion, if $C = \emptyset$, we get $l_e = \lambda_e \leq \max(d_1, \dots, d_e) - m_e =: b$. Otherwise, we conclude that $l_e = \lambda_e \leq \max(\max(C), b)$. Similarly, we can bound the lowest term in g by repeating this procedure and taking the order $<$ with $t_1 < t_2 < \dots < t_e$ and $t_i^a < t_i^b$, iff $a > b$ and replacing the max operation with the min operation, etc. \square

The above results yield, in comparison to Theorem 25, the following less general but simpler (less recursive algorithms) and more flexible (less requirements) toolbox to solve PLDEs in $\Pi\Sigma$ -ring extensions.

Theorem 30. *Let (\mathbb{E}, σ) with $\mathbb{E} = \mathbb{F}\langle t_1 \dots t_e \rangle$ be a $\Pi\Sigma$ -ring extension of a difference field (\mathbb{F}, σ) where for all Π -monomials t_i we have $\frac{\sigma(t_i)}{t_i} \in \mathbb{F}^*$. If one can solve PLDEs, the parameterized pseudo-orbit problem and hypergeometric candidates in (\mathbb{F}, σ) , then one can solve PLDEs in (\mathbb{E}, σ) .*

PROOF. By reordering we may assume that $\mathbb{A} = \mathbb{F}\langle t_1 \dots t_l \rangle$ contains precisely the Π -monomials of \mathbb{E} and that the t_{l+1}, \dots, t_e form all Σ -monomials. By Lemma 29 we can bound the degree of the solutions w.r.t. t_l . By iteration (recursion) we can thus solve PLDEs in (\mathbb{A}, σ) . Finally, with Prop. 27 we can solve PLDEs in (\mathbb{E}, σ) . \square

Combining Theorem 30 with Proposition 21 yields Theorem 31.

Theorem 31. *Let (\mathbb{E}, σ) be an $\text{R}\Pi\Sigma$ -ring extension of a constant-stable difference field (\mathbb{F}, σ) with one R -monomial y with $\frac{\sigma(y)}{y} \in \text{const}_{\sigma}\mathbb{F}$ of order λ and where for each Π -monomial t in the extension \mathbb{E} of \mathbb{F} we have $\frac{\sigma(t)}{t} \in \mathbb{F}^*$. If one can solve PLDEs, solve the parameterized pseudo-orbit problem and can find all hypergeometric candidates in $(\mathbb{F}, \sigma^\lambda)$, one can solve non-degenerated PLDEs in (\mathbb{E}, σ) .*

Using results of [4], this PLDE solver is, e.g., applicable if one specializes \mathbb{F} to the mixed multibasic case introduced in Remark 26.

4 EXAMPLE

We will illustrate the whole machinery by solving the recurrence:

$$\left[(1+n)(2+n) \left((2+n+(1+n) \sum_{i=1}^n \frac{1}{i}) (-1)^n - (1+n)^2 \sum_{i=1}^n \frac{(-1)^i}{i} \right) \right] G(n)$$

$$\begin{aligned}
 & + \left[(1+n)(2+n) \left((2+n+2(1+n) \sum_{i=1}^n \frac{1}{i}) (-1)^n - (1+n) \sum_{i=1}^n \frac{(-1)^i}{i} \right) \right] G(n+1) \\
 & + \left[(1+n)^2(2+n) \left((-1)^n \sum_{i=1}^n \frac{1}{i} + n \sum_{i=1}^n \frac{(-1)^i}{i} \right) \right] G(n+2) \\
 & = (2+n)^2 + (1+n) \sum_{i=1}^n \frac{1}{i} - 2(1+n)^3 (-1)^n \sum_{i=1}^n \frac{(-1)^i}{i}.
 \end{aligned}$$

Internally, we represent the recurrence in the basic $R\Pi\Sigma$ -ring extension (\mathbb{E}, σ) of $(\mathbb{Q}(x), \sigma)$ with $\mathbb{E} = \mathbb{Q}(x)[y][s][\bar{s}]$ where $\sigma(x) = x+1$, $\sigma(y) = -y$, $\sigma(s) = s + \frac{1}{x+1}$ and $\sigma(\bar{s}) = \bar{s} + \frac{-y}{x+1}$. Note that (\mathbb{E}, σ) is an idempotent difference ring of order 2 with $e_0 = \frac{1-y}{2}$ and $e_1 = \frac{1+y}{2}$. Then the recurrence turns into $\sum_{i=0}^2 a_i \sigma^i(g) = \varphi$ with

$$\begin{aligned}
 \mathbf{a} & = \left((1+x)(2+x)(-\bar{s}(1+x)^2 + (2+s+x+sx)y), (1+x)(2+x) \right. \\
 & \quad \left. (-\bar{s}(1+x) + (2+x+2s(1+x))y), (1+x)^2(2+x)(\bar{s}x+sy) \right), \\
 \varphi & = s(1+x) + (2+x)^2 - 2\bar{s}(1+x)^3 y.
 \end{aligned}$$

With Theorem 9 we compute with the package `HarmonicSums` [1] for the first component the equation $\sum_{i=0}^2 b_{i,1} \sigma^{2i}(g_0) = \varphi_0$ with $\mathbf{b}_0 = (b_{i,0}, b_{i,1})$ where

$$\begin{aligned}
 \mathbf{b}_0 & = \left(x(29+33x+11x^2+x^3+2s(6+11x+6x^2+x^3)+\bar{s}(6+11x+6x^2+x^3t)), -x(41+49x+18x^2+2x^3+4s(6+11x+6x^2+x^3)+2\bar{s}(6+11x+6x^2+x^3)), x(2+x)(3+x) \right), \\
 \varphi_0 & = \frac{-x}{(1+x)(2+x)(4+x)} \left(292+559x+387x^2+114x^3+12x^4+4s(22+53x+45x^2+16x^3+2x^4)+2\bar{s}(22+53x+45x^2+16x^3+2x^4) \right).
 \end{aligned}$$

A similar linear difference equation can be computed for the second component. Solving these equations (activating, e.g., Theorem 30 with `Sigma` [21]) leads to the solutions

$$\begin{aligned}
 t_0 & = s + c_1 + c_2(s + \bar{s} + 2x - 4sx - 2\bar{s}x), \\
 t_1 & = -s + d_1 + d_2(-s + \bar{s} - 2x + 4sx - 2\bar{s}x),
 \end{aligned}$$

for $c_1, c_2, d_1, d_2 \in \mathbb{Q}$. Plugging $g := e_0 t_0 + e_1 t_1$ into $\sum_{i=0}^2 a_i \sigma^i(g) = \varphi$ gives us constraints for the constants (compare Theorem 14) and we find $d_1 = -c_1$ and $d_2 = c_2$. These solutions can be combined to the general solution

$$-sy - c_1 y + c_2(\bar{s} - 2\bar{s}x - sy - 2xy - 4sxy),$$

of $\sum_{i=0}^2 a_i \sigma^i(g) = \varphi$, i.e., $\{(0, y), (0, \bar{s} - 2\bar{s}x - sy - 2xy - 4sxy), (1, -sy)\}$ is a basis of $V(\mathbf{a}, (\varphi), \mathbb{E})$. Finally, by reinterpreting the result in terms of sums and products we find the following general solution of the original recurrence:

$$\begin{aligned}
 & - \sum_{i=1}^n \frac{1}{i} (-1)^n - c_1 (-1)^n \\
 & + c_2 \left(-2(-1)^n n - (1+4n)(-1)^n \sum_{i=1}^n \frac{1}{i} + \sum_{i=1}^n \frac{(-1)^i}{i} (1-2n) \right).
 \end{aligned}$$

5 CONCLUSION

We have considered idempotent difference rings (heavily used in the Galois theory of difference equations [10, 27]) and derived a general toolbox to solve PLDEs in this setting. More precisely, we introduced the notion of non-degenerated linear difference operators and showed that finding solutions for a given PLDE in difference rings with zero-divisors can be reduced to finding solutions in difference rings that are integral domains (see Theorems 9 and 14). In the second part of this article we provided two general PLDE solvers: Theorem 25 for the most general case which assumes that rather strong properties hold in the ground field and Theorem 31

which is less general, but where some of the complicated algorithmic assumptions can be dropped. In both cases, the inner core (Theorem 23) is a PLDE solver for $\Pi\Sigma$ -field extensions that has been elaborated in [3] and implemented within `Sigma`.

Our notion of non-degenerated operators is motivated by our method to decompose the desired solution. An interesting question is if there are equivalent (or even more flexible definitions) that are easier to verify. We also indicated that the decomposition method (implemented in the package `HarmonicSums`) works partially if the operator is degenerated. Further investigations in this direction, also connected to the dimension of the solution space, would be highly interesting. Finally, we are strongly motivated to generalize our PLDE solver summarized in Theorem 31 further to more general classes of (basic) $R\Pi\Sigma$ -ring extensions.

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